

DSA3217-PTP/3218-PTP SERIES PRESSURE SCANNER

DIGITAL SENSOR ARRAY

OPERATION AND SERVICE MANUAL



SOFTWARE VERSION 1.00

Scanivalve

PREFACE

WARNINGS, CAUTIONS AND NOTES



WARNING

The WARNING! symbol indicates that danger of injury for persons and the environment and/or considerable damage (mortal danger, danger of injury) will occur if the respective safety precautions are not taken.



CAUTION

The CAUTION ! symbol indicate danger for the system and material if the respective safety precautions are not taken.



The ESD note symbol indicates that proper precautions for handling Electrostatic Sensitive Devices needs to be taken when performing the related operation. This includes the use of grounded work surfaces and personal wrist straps to prevent damage to sensitive electronic components.

WARRANTY

Scanivalve Corporation, Liberty Lake, Washington, hereafter referred to as Seller, warrants to the Buyer and the first end user that its products will be free from defects in workmanship and material for a period of twelve (12) months from date of delivery. Written notice of any claimed defect must be received by Seller within thirty (30) days after such defect is first discovered. The claimed defective product must be returned by prepaid transportation to Seller within ninety (90) days after the defect is first discovered. Seller's obligations under this Warranty are limited to repairing or replacing, at its option, any product or component part thereof that is proven to be other than as herein warranted.

Surface transportation charges covering any repaired or replacement product or component part shall be at Seller's expense; however, inspection, testing and return transportation charges covering any product or component part returned and redelivered, which proves

not to be defective, shall be at the expense of Buyer or the end user, whichever has returned such product or component part.

This Warranty does not extend to any Seller product or component part thereof which has been subjected to misuse, accident or improper installation, maintenance or application; or to any product or component part thereof which has been repaired or altered outside of Seller's facilities unless authorized in writing by Seller, or unless such installation, repair or alteration is performed by Seller; or to any labor charges whatsoever, whether for removal and/or reinstallation of the defective product or component part or otherwise, except for Seller's labor charges for repair or replacement in accordance with the Warranty. Any repaired or replacement product or component part thereof provided by Seller under this Warranty shall, upon redelivery to Buyer, be warranted for the unexpired portion of the original product warranty.

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In the event of a failure:

1) Notify Scanivalve Corporation, Customer Service Department. Include model number and serial number. On receipt of this information, service data or shipping instructions will be forwarded. This may be transacted by telephone or e-mail.

2) On receipt of shipping instructions, forward the product, transportation prepaid. Repairs will be made and the product returned.

3) All shipments should be made via "Best Way". The product should be shipped in the original packing container or wrapped in protective material and surrounded by a minimum of four (4) inches of a shock absorbing material.

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All other brand and product names are trademarks or registered trademarks of their respective companies.

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If the product must be shipped, whether being returned to Scanivalve or relocated to another location it must be packaged properly to minimize the risk of damage. The recommended method of packing is to place the instrument in a container, surrounded on all sides with at least four inches of shock attenuating material such as Styrofoam peanuts.

IMPORTANT NOTICE

Please note that the product specifications and other information contained in this manual are subject to change without notice. Scanivalve Corporation makes an effort and strives to provide complete and current information for the proper use of the equipment. If there are any questions regarding this manual or the proper use of the equipment, contact Scanivalve Corporation.

CONTACT INFORMATION

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TABLE OF CONTENTS

| | |
|---|-----------|
| PREFACE | IV |
| Warnings, Cautions and Notes | iv |
| Warranty | iv |
| Trademarks ® and Copyrights © | v |
| Packaging for Shipment | v |
| Important Notice | v |
| Contact Information | v |
| | |
| SECTION 1: SPECIFICATIONS | 1 |
| DSA3217-PTP | 1 |
| DSA3218-PTP | 2 |
| | |
| SECTION 2: INTRODUCTION | 5 |
| General Description | 5 |
| Module Overview | 5 |
| DAS3217-PTP Configurations | 5 |
| DSA3217-PTP/16Px | 5 |
| DSA3217-PTP/16Px - Dual Range | 6 |
| DSA3217-PTP/8DPx - Differential | 6 |
| DSA3217-PTP/16Px - Absolute | 6 |
| DSA3217-PTP/16Px - Individual Reference | 7 |
| DSA3217-PTP Digital Out Option | 8 |
| DSA3218-PTP Configurations | 9 |
| DSA3218-PTP/16Px | 9 |
| DSA3218-PTP/16Px - Dual Range | 9 |
| DSA3218-PTP/8DPx - Differential | 9 |
| DSA3218-PTP/16Px - Absolute | 10 |
| DSA3218-PTP Heater Option | 10 |
| DSA3218-PTP Cooling Kit Option | 10 |
| Environmental Considerations | 11 |
| | |
| SECTION 3: OPERATION | 12 |
| Unpack & Inventory | 12 |
| Mounting | 12 |
| Warm-up | 12 |
| Communications | 12 |
| Serial Communications | 12 |
| Ethernet Communications | 13 |
| Client/Host Options | 13 |
| PC - TCP/IP | 13 |
| PC - UDP | 14 |
| PC - ScanTel | 14 |
| PC - LabVIEW Configuration Utility | 14 |
| PC - LabVIEW Development Kit | 14 |
| PC - OPC Server | 14 |
| PC - HyperTerminal | 14 |

| | |
|-------------------------------------|-----------|
| Zero Offset Calibration | 14 |
| Quick Zero Jumper | 15 |
| Scanning | 15 |
| Scanning With An External Trigger | 15 |
| Hardware Trigger | 15 |
| Software Trigger | 15 |
| Freon Application Operations | 16 |
| | |
| SECTION 4: HARDWARE | 17 |
| Pneumatic Connections | 17 |
| Making 1/16" Tubulation Connections | 17 |
| Pressure Measurement (Px) Ports | 18 |
| Calibration (CAL) Port | 18 |
| Reference (REF) Port | 18 |
| Control 1 (CLT1) Port | 18 |
| Control 2 (CTL2) Port | 18 |
| Control Supply (CTL SUPPLY or CTL) | 18 |
| Return (RTN) Port | 18 |
| Purge Control (PRGCTL) Port | 19 |
| Purge Supply (PRG) Port | 19 |
| Power Requirements | 19 |
| Calibration Valve | 19 |
| | |
| SECTION 5: SOFTWARE | 21 |
| DSA-PTP Control and Configuration | 21 |
| DSA-PTP Commands | 21 |
| Command List | 22 |
| CALCTEMP | 22 |
| Calibrate | 23 |
| Calibrate Barometric Pressure | 24 |
| Calibrate Zero | 25 |
| Clear | 25 |
| Delete | 26 |
| Error | 26 |
| Fill | 27 |
| Insert | 27 |
| List All | 28 |
| List All Ranges | 29 |
| List Calibrate | 30 |
| List Delta | 30 |
| Digital Output | 31 |
| LIST FTP Settings (LIST FTP) | 31 |
| List Gain | 32 |
| List Identification | 32 |
| LIST IP Settings (LIST IP) | 33 |
| List Master | 34 |
| List MAXn Pressures | 35 |
| List MINn Pressures | 35 |
| List Negative Points | 36 |
| List Offset | 36 |
| List PTP Variables | 37 |

| | |
|-------------------------------------|-----------|
| List Scan | 37 |
| List Temperature | 38 |
| List Zero | 39 |
| Save | 39 |
| Scan | 40 |
| Scan Trigger | 41 |
| Set | 41 |
| Status | 42 |
| Stop | 42 |
| Upload | 42 |
| Version | 43 |
| Set PTP Time | 43 |
| Get PTP Time | 43 |
| Get UTC Offset | 43 |
| Configuration Variables | 44 |
| Scan Variables (LIST S) | 44 |
| Average (AVG) | 44 |
| Binary Data (BIN) | 44 |
| Unit Conversion Factor (CVTUNIT) | 44 |
| Engineering Units (EU) | 45 |
| Data Format (FORMAT) | 45 |
| Frames Per Scan (FPS) | 45 |
| Page (PAGE) | 46 |
| Period (PERIOD) | 46 |
| QPKTS | 46 |
| Data Sample Source (SIM) | 46 |
| Time Stamp (TIME) | 47 |
| Scan Unit (UNITSCAN) | 47 |
| Enable External Trigger (XSCANTRIG) | 47 |
| Zero Correction (ZC) | 48 |
| IP Variables (LIST IP) | 49 |
| IP Address (IPADD) | 49 |
| Subnet Mask (SUBNET) | 49 |
| MAC Address (MAC) | 49 |
| LOGIN (LOGIN) | 49 |
| Password (PASSWORD) | 50 |
| Login 1(LOGIN1) | 50 |
| Password 1(PASSWORD1) | 50 |
| Anonymous Logon (ALLOWANON) | 50 |
| Application (APP) | 50 |
| Set Gateway (GW) | 51 |
| PTP Variables (LIST PTP) | 52 |
| PTP Enable (PTPEN) | 52 |
| PTP Statistics (STAT) | 52 |
| Scan Start Time (SST) | 52 |
| Scan Start Date (SSD) | 53 |
| UTC Offset (UTCOFFSET) | 53 |
| FTP Variables (LIST FTP) | 54 |
| FTP User Name (UESRFTP) | 54 |
| FTP Password (PASSFTP) | 54 |
| Enable FTP (ENFTP) | 54 |
| FTP File Path (PATHFTP) | 54 |
| FTP IP Address(IPFTP) | 54 |

| | |
|--|-----------|
| FTP File Name(FILEFTP) | 55 |
| Pressure Variables (LIST B, LIST H, LIST L and LIST N) | 56 |
| Absolute Enable (ABS _n) | 56 |
| Maximum Pressure (MAX _n) | 56 |
| Minimum Pressure (MIN _n) | 56 |
| Negative Calibration Points (NEGPTS _n) | 56 |
| Calibration Variables (LIST C) | 57 |
| Channel 1-8 Number of Negative Calibration Points (NEGPTSL) | 57 |
| Channel 9-16 Number of Negative Calibration Points (NEGTPSH) | 57 |
| Channel 1-8 Maximum Pressure (PMAXL) | 57 |
| Channel 9-16 Maximum Pressure (PMAXH) | 57 |
| Channel 1-8 Minimum Pressure (PMINL) | 58 |
| Channel 9-16 Minimum Pressure (PMINH) | 58 |
| Identification Variables (LIST I) | 59 |
| Serial Echo (ECHO) | 59 |
| Model (MODEL) | 59 |
| Ethernet Port (PORT) | 59 |
| Ethernet Host (HOST) | 60 |
| Pressure Deltas (LIST D) | 60 |
| Deltas (DELTA _n) | 60 |
| Temperature Offsets (LIST O) | 60 |
| Temperature Offset (TEMPB _n) | 60 |
| Temperature Gains (LIST G) | 61 |
| Temperature Gain (TEMPM _n) | 61 |
| Temperature Coefficients (LIST TEMP) | 61 |
| Temperature Coefficients (TEMP _n) | 61 |
| Zero Offsets (LIST Z) | 61 |
| Zero Offset (ZEROn) | 61 |
| DSA-PTP Packet Definitions | 62 |
| Packet Types | 62 |
| Host to DSA-PTP Command Packet | 62 |
| DSA-PTP to Host Scan Packet (Not Used) | 63 |
| Status Packet | 63 |
| Scan Raw Packet | 63 |
| Scan EU Packet | 64 |
| Scan Raw with Time Packet | 64 |
| Scan EU with Time Packet | 64 |
| ASCII Packet | 64 |
| ASCII Packet Examples | 65 |
| Network Protocols Supported | 65 |
| DSA3200-PTP Boot Parameters | 65 |
| Changing Boot Parameters (including IP address) | 65 |
| DSA3200-PTP Buffer Description | 65 |
| DSA-PTP Network Configurations | 65 |
| Isolated Network | 65 |
| Integrated with System Network | 65 |
| Sub-Network with Gateway | 66 |
| DSA-PTP Network Addressing | 66 |
| SECTION 6: MAINTENANCE | 67 |

| | |
|---|-----------|
| Calibration | 67 |
| Full Calibrations | 67 |
| Field Calibrations | 67 |
| Zero Offset Calibration | 67 |
| Special Procedures | 68 |
| Internet Explorer Setup | 68 |
| DSA-PTP Firmware Installation (Windows 7 & 10) | 68 |
| DSA-PTP Coefficient Upload | 69 |
| DSA3200-PTP Sensor Replacement | 70 |
| DSA3200-PTP General Checkout Procedure | 73 |
| APPENDIX | 76 |
| Appendix A: Temperature Compensated Pressure Conversion | 76 |
| Appendix B: Engineering Unit Conversion Constants | 77 |
| Appendix C: DSA3200-PTP Error List | 78 |
| Boot/Initialization Errors | 78 |
| Set Configuration Variable Errors | 78 |
| Command Errors | 80 |
| Communication Errors | 81 |
| Appendix D: Software Change Log | 83 |

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SECTION 1: SPECIFICATIONS

DSA3217-PTP

| | |
|---|---|
| Size (WxHxD) | 2.86" x 3.40" x 7.08" (7.26cm x 8.64cm x 17.98cm) |
| Weight | 6.4lbs (2.91kg) |
| Pressure Inputs: | 16 (Standard) 8 (True Differential) |
| Input Fittings: | |
| Pressure Inputs | .063" tubulations |
| Control Inputs | .063" tubulations |
| Full Scale Ranges (standard) | |
| Differential | ±5"WC, ±10"WC, ±20"WC, 1, 2.5, 5, 15, 30, 50, 100, 250, 500, 750 psid (1.25, 2.5, 5, 7, 17, 35, 100, 210, 345, 700, 1725, 3500, 5170 kPa) |
| Absolute | 15, 30, 50, 100 and 250 psia (100, 210, 345, 700 and 1725 kPa) |
| Accuracy (after calibration)* | |
| Differential | |
| 5 inH ₂ O | ±0.40% FS |
| 10 inH ₂ O | ±0.20% FS |
| 20 inH ₂ O | ±0.20% FS |
| 1.0 psid | ±0.12% FS |
| 2.5 psid | ±0.08% FS |
| 5 to 500 psid | ±0.05% FS |
| 501 to 750 psid | ±0.08% FS |
| Absolute (With CALB performed) | |
| 15 psia | ±0.05% FS |
| 30 psia | ±0.05% FS |
| 50 psia | ±0.05% FS |
| 100 psia | ±0.05% FS |
| 250 psia | ±0.05% FS |
| *Some combinations of pressure ranges in dual-range modules may dictate a reduction in accuracy | |
| Overpressure Capacity (No damage) | |
| 5 inH ₂ O | 2 psi |
| 10 inH ₂ O | 2 psi |
| 20 inH ₂ O | 2 psi |
| 1 psid | 5 psi |
| 2.5 to 499 psid | 200% |
| 500 psid | 150% |
| 750 psid | 113% |

| | |
|---|--|
| Maximum Reference Pressure | 250 psid (1750 kPa) or sensor overpressure, which ever is less |
| Power Requirements | 20 to 36 Vdc at 8 W |
| I/O and mating connectors | |
| Ethernet 10Base-T | RJ45 |
| Trigger (bulkhead) | PTO2A-8-2P |
| Trigger (mating) | PTO6A-8-2S-SR |
| Trigger (bulkhead) | JTP02RE8-6P |
| Trigger (mating) | JTO1RE8-6S-SR |
| Power (bulkhead) | PTO2A-8-3P |
| Power (mating) | PTO6A-8-3S-SR |
| Communications Protocol | Ethernet IEEE802.3 |
| Typical Data Acquisition Rate* | |
| TCP/IP ASCII | 70 samples/chan/sec |
| UDP Binary | 850 samples/chan/sec |
| *Maximum data output depends on network | |
| Typical Communications Rate | |
| Ethernet | 100 Mbits/sec |
| RS232 | 9600 BAUD (Configuration only) |
| Operating Temperature | 0 to 60 °C |
| Compensated Range | 0 to 69 °C |
| Total Thermal Error | Less than ±0.001% FS |
| Humidity | |
| Operation | 5 to 95% RH, Non-Condensing |
| Storage | 5 to 95% RH, Non-Condensing |
| Shock & Vibration | MIL-STD-810D Curve H |
| Shock | 10G |
| Vibration | 10G |
| Acceleration | 10G |
| Media | Gasses compatible with Silicon, Silicone, Aluminum and Stainless Steel |
| Precision Time Protocol | IEEE-1588 PTP v2 |

DSA3218-PTP

| | |
|---|---|
| Size (WxHxD) | 4.08" x 6.97" x 9.0" (10.36 cm x 17.70 cm x 22.86 cm) |
| Weight | 9.78 lbs (4.45 kg) |
| Pressure Inputs: | 16 (Standard) 8 (True Differential) |
| Input Fittings: | |
| Pressure Inputs | 1/8" SwageLok® (1/16" and 1/4" optional) |
| Control Inputs | 1/8" SwageLok® (1/16" and 1/4" optional) |
| Full Scale Ranges | |
| Differential | ±5"WC, ±10"WC, ±20"WC, 1, 2.5, 5, 15, 30, 50, 100, 250, 500, 750 psid (1.25, 2.5, 5, 7, 17, 35, 100, 210, 345, 700, 1725, 3500, 5170 kPa) |
| Absolute | 15, 30, 50, 100 and 250 psia (100, 210, 345, 700 and 1725 kPa) |
| Accuracy (after calibration)* | |
| Differential | |
| 5 inH ₂ O | ±0.40% FS |
| 10 inH ₂ O | ±0.20% FS |
| 20 inH ₂ O | ±0.20% FS |
| 1.0 psid | ±0.12% FS |
| 2.5 psid | ±0.08% FS |
| 5 to 500 psid | ±0.05% FS |
| 501 to 750 psid | ±0.08% FS |
| Absolute (With CALB performed) | |
| 15 psia | ±0.05% FS |
| 30 psia | ±0.05% FS |
| 50 psia | ±0.05% FS |
| 100 psia | ±0.05% FS |
| 250 psia | ±0.05% FS |
| *Some combinations of pressure ranges in dual-range modules may dictate a reduction in accuracy | |
| Overpressure Capacity (No damage) | |
| 5 inH ₂ O | 2psi |
| 10 inH ₂ O | 2psi |
| 20 inH ₂ O | 2psi |
| 1.0 psid | 5psi |
| 2.5 to 499 psid | 200% |
| 500 psid | 150% |
| 750 psid | 113% |

| | |
|---|---|
| Maximum Reference Pressure | 250 psid (1750 kPa) or sensor overpressure, which ever is less |
| Power Requirements | |
| No Heater | 22 to 36 Vdc at 8 W |
| With Heater | 22 to 36 Vdc at 35 W (Drops to 8 W after module has reached temperature) |
| I/O and mating connectors | |
| Ethernet 10Base-T | D-Code M12 |
| Trigger (bulkhead) | PTO2A-8-2P |
| Trigger (mating) | PTO6A-8-2S-SR |
| Trigger (bulkhead) | JTO2RE8-6P |
| Trigger (mating) | JTO1RE8-6S-SR |
| Power (bulkhead) | PTO2A-8-3P |
| Power (mating) | PTO6A-8-3S-SR |
| Communications Protocol | Ethernet IEEE802.3 |
| Typical Data Acquisition Rate* | |
| TCP/IP ASCII | 70 samples/chan/sec |
| UDP Binary | 850 samples/chan/sec |
| *Maximum data output depends on network | |
| Typical Communications Rate | |
| Ethernet | 100 Mbits/sec |
| RS232 | 9600 BAUD (Configuration only) |
| Operating Temperature | |
| Without Heater | 0 to 60 °C |
| With Heater | -55 to 60 °C (Cooling kit recommended above 55 °C) |
| Compensated Range | 0 to 69 °C |
| Total Thermal Error | Less than ±0.001% FS |
| Humidity | |
| Operation | 5 to 95% RH, Non-Condensing |
| Storage | 5 to 95% RH, Non-Condensing |
| Shock & Vibration | MIL-STD-810D Curve H |
| Shock | 10G |
| Vibration | 10G |
| Acceleration | 10G |
| Media | Gasses compatible with Silicon, Silicone, Aluminum and Stainless Steel |
| Precision Time Protocol | IEEE-1588PTP v2 |

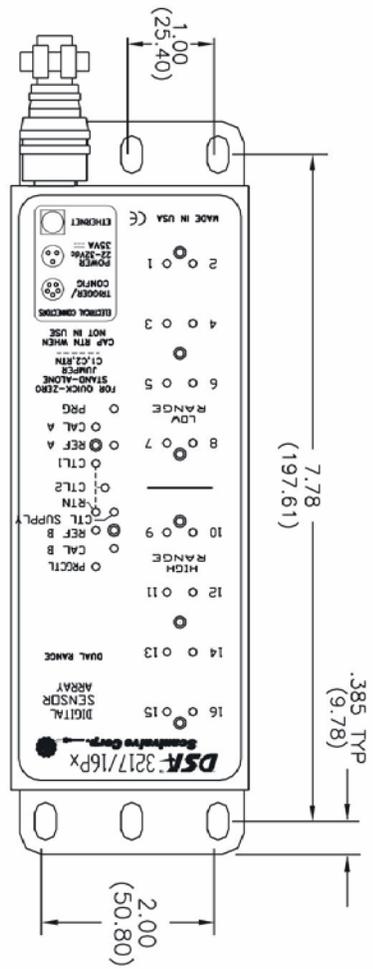
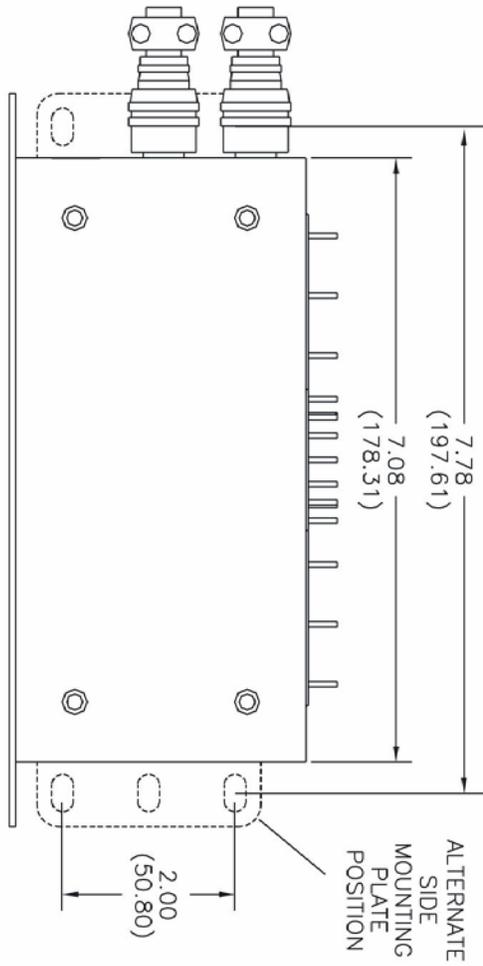
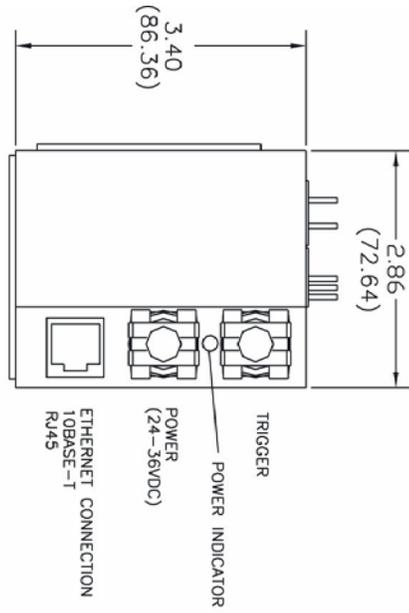


FIGURE 1.1 - DSA3217-PTP

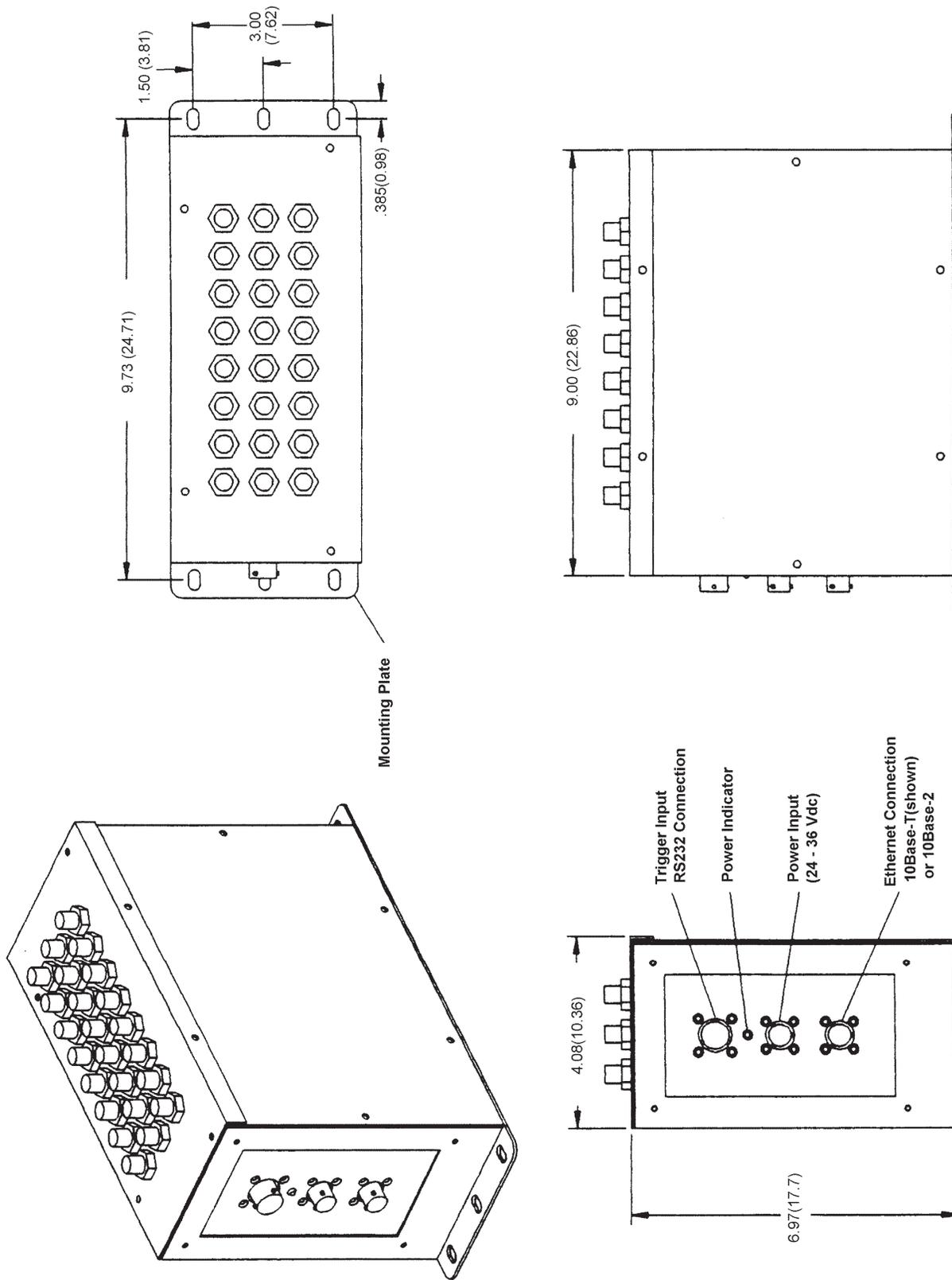


FIGURE 1.2 - DSA3218-PTP

SECTION 2: INTRODUCTION

GENERAL DESCRIPTION

The Digital Sensor Array (DSA) is a stand-alone electronic pressure scanner which can accept up to 16 pneumatic inputs. The module is specifically designed for use in applications where long calibration intervals, simple operation and high accuracy are required. Each DSA-PTP incorporates 16 individual, temperature compensated, piezoresistive pressure sensors, an A/D converter and a microprocessor. Each pressure sensor is characterized over pressure and temperature. This information is stored in EEPROM memory and enables the module to directly output corrected data in engineering units.

The sensors within each DSA3200-PTP series module are arranged in groups of eight (8). Each block of eight (8) sensors has its own calibration valve. This calibration valve has four (4) modes of operation and allows the DSA-PTP module to perform measurement, calibration and purge functions. The four (4) modes are:

- Measure
- Calibrate
- Isolate
- Purge

The calibration valve mode is selected by applying 90-120 psi control pressure configurations unique for each operation mode. The DSA-PTP calibration valve utilizes "Normally Px" valve logic where the valve defaults to the measurement mode when no control pressures are applied.

MODULE OVERVIEW

The DSA3200-PTP series is available in two basic configurations; the DSA3217-PTP and the DSA3218-PTP. Both configurations offer 16 pressure inputs, both operate using the same software commands and both offer corrected data output directly in engineering units. The difference between the modules is the packaging and the intended applications. The DSA3217-PTP is enclosed in a stainless steel, splash resistant enclosure intended for most laboratory, educational or controlled environments. The DSA3218-PTP however, is enclosed in a stainless steel, splash resistant, shock mounted enclosure with Swagelok® fittings on all pneumatic connections. It is intended for applications such as gas turbine testing, flight testing, industrial applications and other more rugged environments.

In addition to the more rugged casing on the DSA3218-PTP modules, additional options of a heater or a cooling kit are offered. The heater option allows the module to be operated below the 0 °C temperature compensation range of the standard DSA3218-PTP or DSA3217-PTP modules. The cooling kit is recommended for applications where the ambient environment temperatures are likely to exceed 55 °C.

Both DSA3217-PTP and DSA3218-PTP modules are available with a variety of sensor configurations. The standard configuration is 16 channels of the same pressure range, however modules can be configured as dual-range units with 8 channels of one pressure range and 8 channels of another pressure range, 'True-Differential' measurement modules which provide 8 channels of differential pressure measurement, absolute pressure measurement modules or units with individual reference ports for each sensor (DSA3217-PTP only).

DAS3217-PTP CONFIGURATIONS

The DSA3217-PTP is available in 5 basic configurations.

DSA3217-PTP/16Px

The basic DSA3217-PTP/16Px module provides 16 channels of the same 'gauge' pressure range sensors. These 16 pressure transducers are configured into two (2) groups of eight (8) each. Each group of eight (8) transducers shares a common calibration valve and a common reference manifold. Single range modules tie the two reference manifolds together and the two calibration valves to provide the user with a single reference and a single calibration port to connect to. Figure 2.1 depicts the top panel of a standard DSA3217-PTP/16Px.

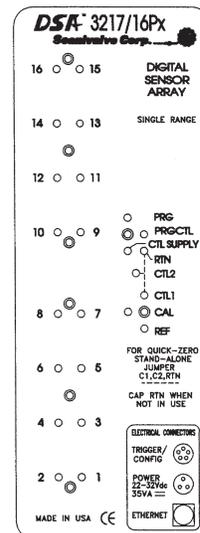


FIGURE 2.1 - DSA3217-PTP/16Px TOP PANEL

DSA3217-PTP/16Px - DUAL RANGE

The DSA3217-PTP/16Px module is available as a dual-range module, offering eight (8) channels of one pressure range and eight (8) channels of a different pressure range. Like a standard DSA3217-PTP, each group of eight (8) transducers share a common calibration valve and a common reference manifold. However, in dual range modules the reference manifolds and the calibration valves are not tied together and separate reference and calibration ports are provided on the top of the module. They are labeled CAL, CAL B, REF and REF B. Figure 2.2 depicts the top panel of a dual range DSA3217-PTP/16Px module.

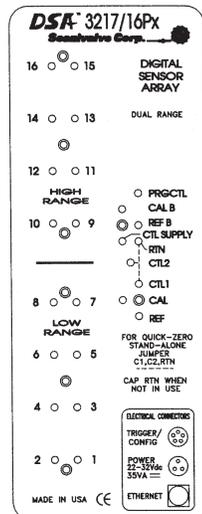


FIGURE 2.2 - DSA3217-PTP/16Px DUAL RANGE TOP PANEL

DSA3217-PTP/8DPx - DIFFERENTIAL

For differential pressure measurement applications, the DSA3217-PTP can be configured with eight (8) differential pressure transducers. They are arranged into two (2) groups of four (4) transducers. Like the DSA3217-PTP/16Px, each group of transducers has a dedicated calibration valve that allows the input pressures to be blocked off during any calibration, including a zero offset calibration (CALZ). Figure 2.3 depicts the top panel of a DSA3217-PTP/8DPx module.

DSA3217-PTP/16Px - ABSOLUTE

The DSA3217-PTP/16Px module can be used for absolute pressure measurement when equipped with absolute pressure transducers. A calibration valve is provided for each group of eight (8) sensors. All sixteen (16) transducers are tied a single calibration port, except in the cases of dual-range absolute modules. Figure 2.4 depicts the top panel of a DSA3217-PTP/16Px absolute pressure module.

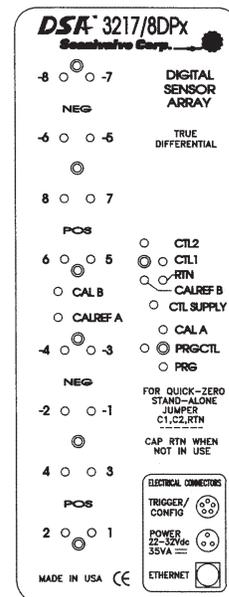


FIGURE 2.3 - DSA3217-PTP/8DPx DIFFERENTIAL TOP PANEL

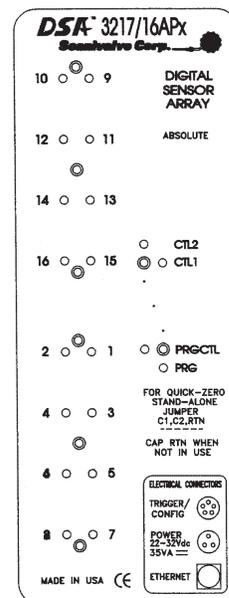


FIGURE 2.4 - DSA3217-PTP/16Px ABSOLUTE TOP PANEL

DSA3217-PTP/16Px - INDIVIDUAL REFERENCE

Both the standard DSA3217-PTP/16Px and Dual Range DSA3217-PTP/16Px are available with individual reference ports for each sensor. A calibration valve is provided for each group of eight (8) sensors, however unlike the standard DSA3217-PTP/16Px modules a separate reference port is provided for all sixteen (16) transducers. These individual reference ports are not controlled by the calibration valve.

This means that any calibration, including a zero offset calibration (CALZ) will have to be done with no pressure applied to the module. The individual reference modification is depicted in Figure 2.5 below.

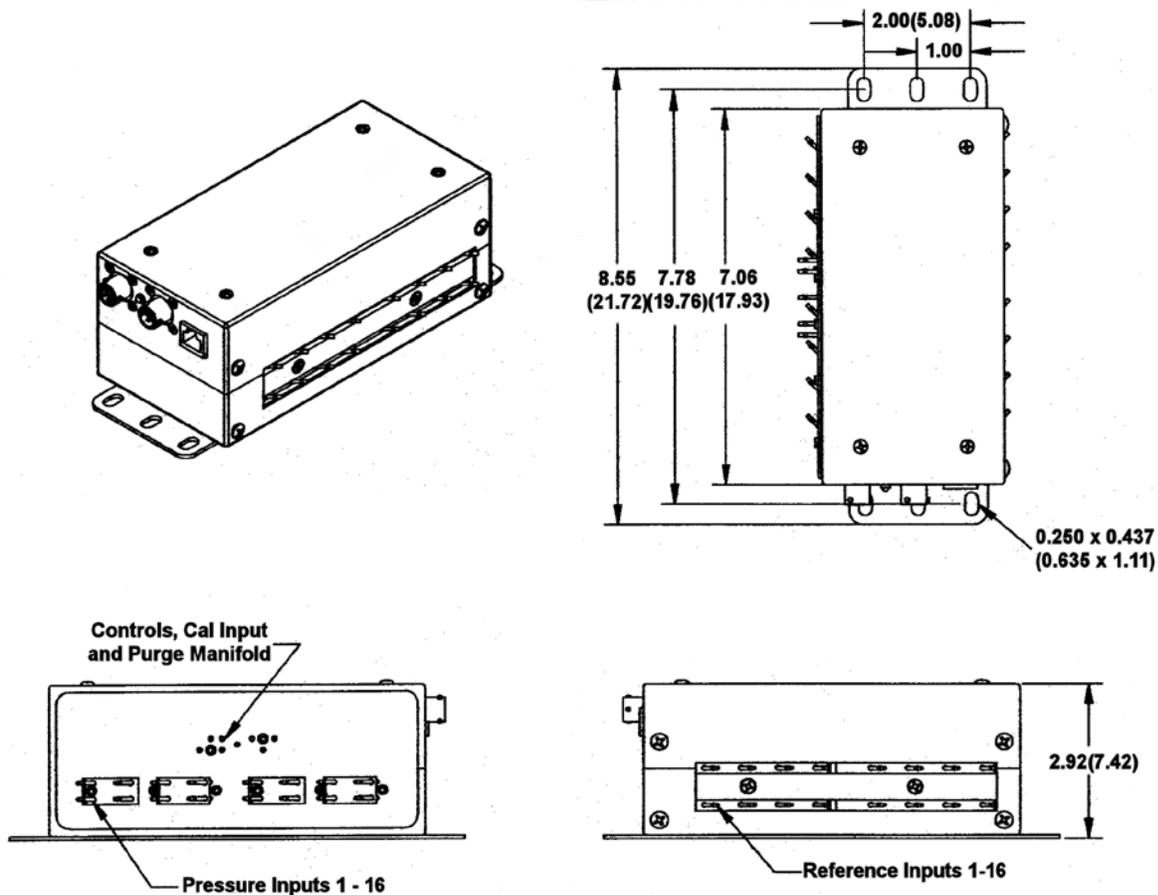
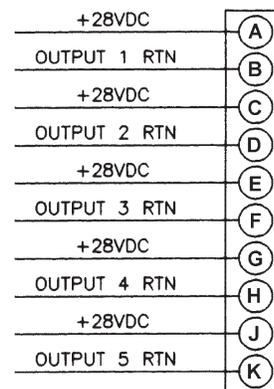


FIGURE 2.5 - DSA3217-PTP/16Px INDIVIDUAL REFERENCE

DSA3217-PTP DIGITAL OUT OPTION

An additional option that can be added to DSA3217-PTP/16px, DSA3217-PTP/16px Dual Range, DSA3217-PTP/8dPx Differential pressure and DSA3217-PTP/16px Absolute pressure modules is the Digital Out controller. This is an external option that allows the DSA-PTP module to send up to five (5) Digital Output (DOU) signals. The Digital Out option is shown below in Figure 2.6.

The Digital Out option does increase the power requirements for the DSA3217-PTP. The power supply must be capable of supporting the standard power requirement of the DSA3217-PTP and the power requirements for the Digital Out option. Each Digital Out being used requires 500mA @ 24Vdc. Figure 2.7 shows the wiring diagram of the Digital Out connector.



PT02A-12-10S

FIGURE 2.7 - DSA3217-PTP DIGITAL OUTPUT WIRING DIAGRAM

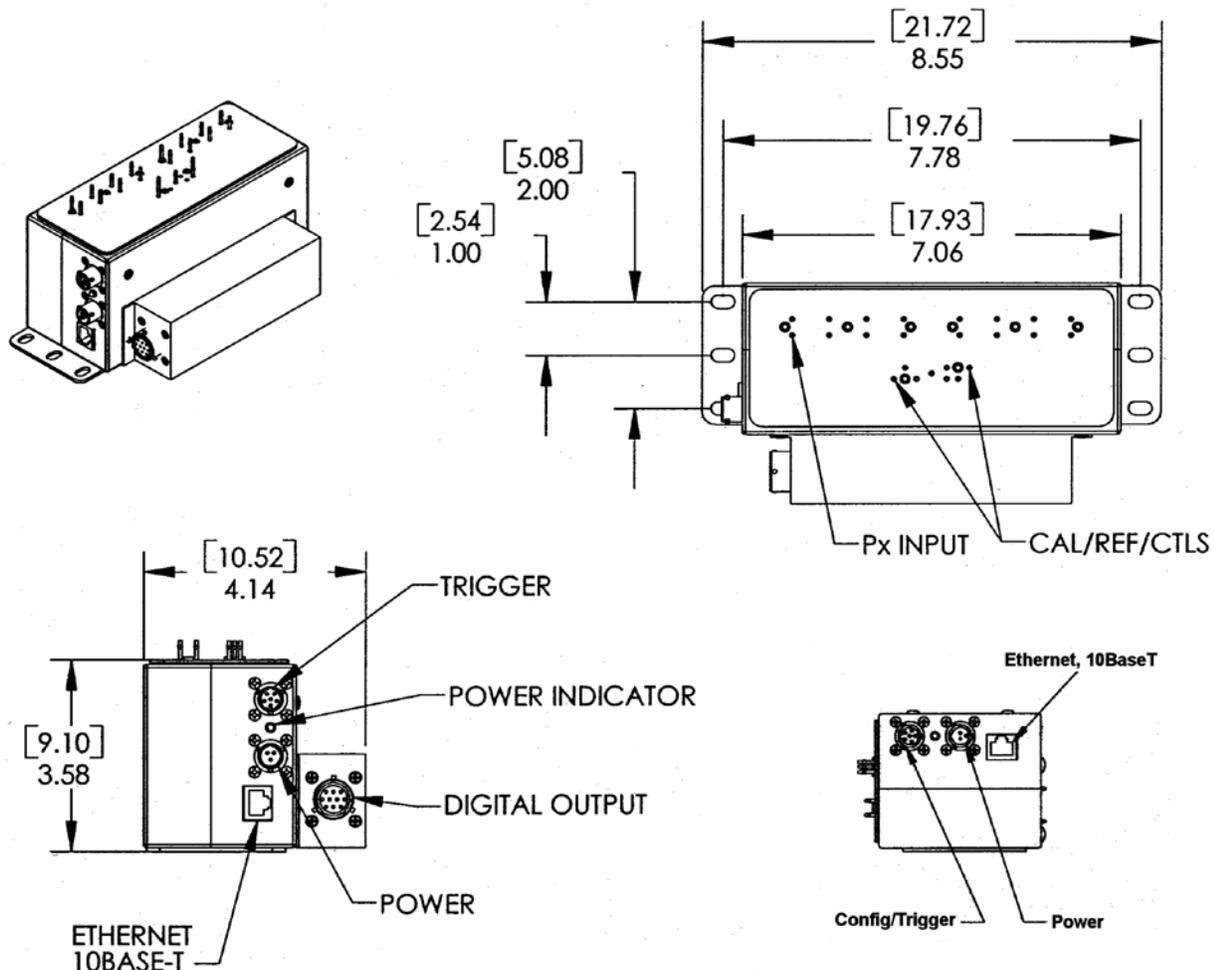


FIGURE 2.6 - DSA3217-PTP DIGITAL OUT OPTION

DSA3218-PTP CONFIGURATIONS

The DSA3218-PTP is available in 4 basic pressure configurations and has 2 optional hardware configurations.

DSA3218-PTP/16Px

The basic DSA3218-PTP/16Px module provides 16 channels of the same ‘gauge’ pressure range sensors. These 16 pressure transducers are configured into two (2) groups of eight (8) each. Each group of eight (8) transducers shares a common calibration valve and a common reference manifold. Single range modules tie the two reference manifolds together and the two calibration valves to provide the user with a single reference and a single calibration port to connect to. Figure 2.8 depicts the top panel of a standard DSA3217-PTP/16Px.

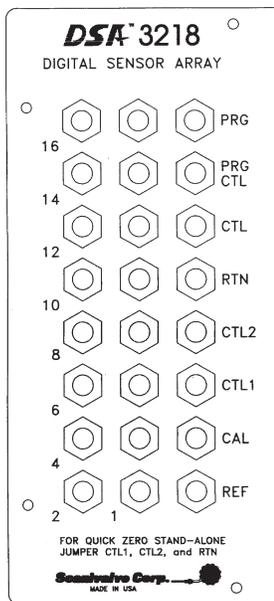


FIGURE 2.8 - DSA3218-PTP/16Px TOP PANEL

DSA3218-PTP/16Px - DUAL RANGE

The DSA3218-PTP/16Px module is available as a dual-range module, offering eight (8) channels of one pressure range and eight (8) channels of a different pressure range. Like a standard DSA3218-PTP, each group of eight (8) transducers share a common calibration valve and a common reference manifold. However, in dual range modules the reference manifolds and the calibration valves are not tied together and separate reference and calibration ports are provided on the top of the module. They are labeled CAL A, CAL B, REF A and REF B. Figure 2.9 depicts the top panel of a dual range DSA3218-PTP/16Px module.

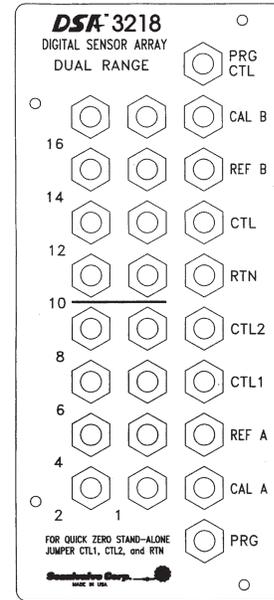


FIGURE 2.9 - DSA3218-PTP/16Px DUAL RANGE TOP PANEL

DSA3218-PTP/8DPx - DIFFERENTIAL

For differential pressure measurement applications, the DSA3218-PTP can be configured with eight (8) differential pressure transducers. They are arranged into two (2) groups of four (4) transducers. Like the DSA3218-PTP/16Px, each group of transducers has a dedicated calibration valve. Figure 2.10 depicts the top panel of a DSA3218-PTP/8DPx module.

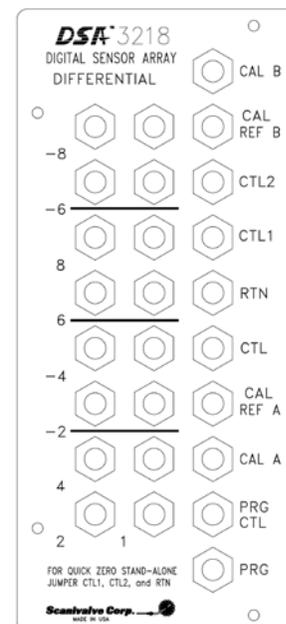


FIGURE 2.10 - DSA3218-PTP/8DPx DIFFERENTIAL TOP PANEL

DSA3218-PTP/16Px - ABSOLUTE

The DSA3218-PTP/16Px module can be used for absolute pressure measurement when equipped with absolute pressure transducers. A calibration valve is provided for each group of eight (8) sensors. All sixteen (16) transducers are tied a single calibration port, except in the cases of dual-range absolute modules. Figure 2.11 depicts the top panel of a DSA3218-PTP/16Px absolute pressure module.

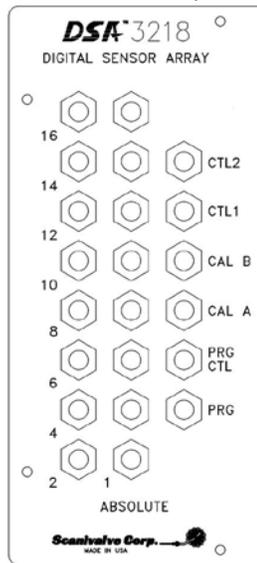


FIGURE 2.11 - DSA3218-PTP/16Px ABSOLUTE TOP PANEL

DSA3218-PTP HEATER OPTION

The DSA3218-PTP series module can be equipped with an internal heater for cold environment applications. The heater kit option increases the DSA3218-PTP’s operational ambient temperature range to -55°C to 60°C by maintaining the internal temperature of the module at approximately +20°C. With a heater installed, the power requirements for the DSA3218-PTP module increase to: 22-36Vdc @ 35W (28Vdc nominal). The power consumption of the module will decrease once the temperature of the module has stabilized.

DSA3218-PTP COOLING KIT OPTION

For applications where the DSA3218-PTP module must operate in ambient temperatures above the specified operating range, a cooling kit option is available. The cooling kit provides two (2) 3/8” Swagelok® fittings on the outside of the case and internal baffling to allow cool Nitrogen (or clean, dry air) to be circulated through the unit. The exact cooling flow requirements and the maximum operating temperature are different for each application, but for most applications the DSA3218-PTP can be operated up to 80°C ambient temperature if sufficient cooling flow is provided. For most cases, 2-3 SCFM of 25°C should be supplied into the module.

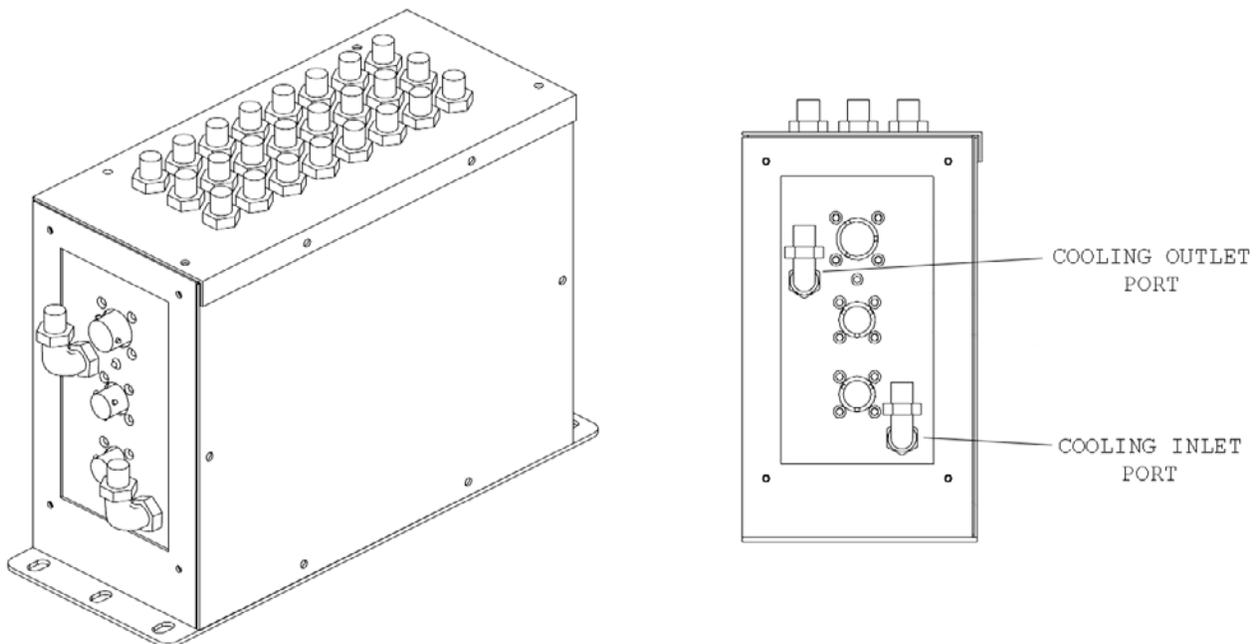


FIGURE 2.12 - DSA3218-PTP COOLING KIT OPTION

ENVIRONMENTAL CONSIDERATIONS

Both the DSA3217-PTP and DSA3218-PTP modules are constructed with a rugged, corrosion resistant stainless steel case. This case is designed with withstand normal industrial, flight test, educational, wind tunnel or similar environments. The case is splash resistant but not water proof. If any moisture gets spilled or splashed on the DSA-PTP module, wipe it dry immediately to prevent damage to the module. The DSA-PTP module should not be mounted outdoors.

The DSA3218-PTP module is designed for more rugged applications and incorporates internal shock mounts for vibration isolation, Swagelok® compression fittings on all pneumatic connections and robust, Bendix/Amphenol connectors for power, serial and Ethernet connections.

Both DSA-PTP modules include a heavy-duty mounting plate and can be mounted in any orientation. Once mounted, a zero offset calibration (CALZ) can be performed to remove any offset caused by the module orientation.

The DSA-PTP module should not be mounted in a location where it may be subjected to extreme temperature shifts or ambient temperatures outside of the specified operating range of the module. Keep in mind that the internal temperature of the module will run several degrees warmer than ambient temperature.

SECTION 3: OPERATION

UNPACK & INVENTORY

When you first unpack the DSA-PTP module, begin by inspecting and inventorying the contents of the package. If any visible damage is immediately noticed or if any contents are missing, contact Scanivalve before proceeding. Standard modules are shipped with the following contents as a minimum:

1. DSA3217-PTP or DSA3218-PTP module
2. Certificate of calibration
3. Full calibration report
4. DSA-PTP resource Drive
5. Quick-zero jumper
6. Trigger/configuration cable connector
7. Power cable connector
8. Ethernet cable connector (DSA3218-PTP only)

MOUNTING

The DSA-PTP module comes with a 3/32" (2.4mm) mounting plate attached to the bottom. This accepts mounting hardware up to 1/4" (6.4mm) in diameter. For added flexibility, the mounting plate on DSA3217-PTP modules can be removed from the bottom of the module and mounted on the side of the module. The DSA-PTP module can be mounted in any orientation as any offsets caused by gravity will be removed by a zero offset calibration (CALZ). Ensure that the DSA-PTP module is mounted in an environment that conforms to the requirements described in "*Environmental Considerations*" on page 11.



CAUTION

CAUTION! Mounting the DSA-PTP module inadequately or in an environment that does not conform to the recommendations can result in permanent damage to the module.

WARM-UP

After applying power to the DSA-PTP module, a minimum of 30 minutes before collecting data is required to allow the module temperature to become stable. It is recommended that if time allows, the warm-up period should be extended to one hour for most applications.

COMMUNICATIONS

The DSA-PTP module is designed primarily for Ethernet communications. This provides a means to configure the DSA-PTP module as well as scan and collect data from the module.

A serial RS-232 port is also provided. The serial connection is designed to be used to configure the module, upload operating system upgrades and provide emergency communications. Several important module variables can be configured through the serial port, but possibly the most important is the Ethernet IP address.

SERIAL COMMUNICATIONS

Every DSA3200-PTP module has an RS-232 serial output. It is available through the 'Serial Communications/Trigger' connector on the front face of the module. For both DSA3217-PTP and DSA3218-PTP modules, the bulkhead connector on the module is an Amphenol JTP02RE8-6P (or PT02A-8-2P on serial numbers pre 180). All DSA-PTP modules are shipped with a mating connector (Amphenol JT06RE8-6S-SR) that can be used to fabricate a Serial Communications/Trigger cable. Alternately, a Serial Communication/Trigger cable can be ordered from Scanivalve using the Scanivalve part number 155829.

The wiring diagram for the RS-232 output is shown below. The cable wiring must connect the Tx output from the host computer to the Rx input of the DSA-PTP module. Also, the RX input of the host computer must connect to the Tx output of the DSA-PTP module.

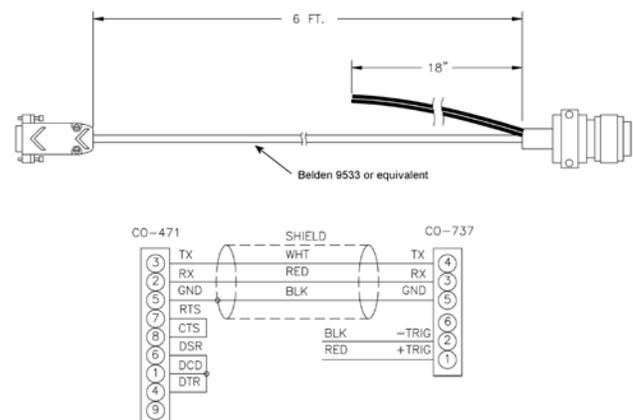


FIGURE 3.1 - SERIAL COMMUNICATION/TRIGGER CABLE

Settings for establishing a serial connection to the DSA-PTP module are as follows:

- Bits per second: 9600 BAUD
- Data bits: 8
- Parity: none
- Stop bits: 1
- Flow control: none

The Serial Communications port also serves as the input for the external scan trigger. For more information on externally triggering scans, see “Scanning With An External Trigger” on page 15.

For information on changing the boot parameters including the module’s Ethernet IP address, see “Changing Boot Parameters (including IP address)” on page 65.

ETHERNET COMMUNICATIONS

The primary means of communication with the DSA3217-PTP and DSA3218-PTP module is the 100Base-T Ethernet port. All DSA3217-PTP modules use a standard RJ-45 Ethernet port. For added ruggedness, all DSA3218-PTP modules use a M12 D Code connector for the Ethernet connection instead of a standard RJ-45. Shielded Category 5 cable or better is recommended for all Ethernet connections. The Ethernet cable used will need to be either a straight through (pin to pin) cable or a crossed cable depending on the Ethernet network structure being used. A straight cable will be used if the DSA-PTP module is being connected to the host computer through a network hub or switch. If the DSA-PTP module is being connected directly to the network port on the host computer, a crossed Ethernet cable must be used.

Ethernet cables for the DSA3218-PTP modules can be ordered from Scanivalve in any length up to 100 feet (30 meters).

Before an Ethernet connection can be established the IP address need to be configured. In order to be compatible, the IP address of the module and host computer must share the first two octets. The third and fourth octets of the IP address is variable, although it is recommended that the third octet also be shared between the host computer and the module.

Example of matching the first three octets (recommended):

- Host computer: 191.30.80.100
- DSA-PTP module: 191.30.80.125

Example of matching the first two octets:

- Host computer: 191.30.1.100
- DSA-PTP module: 191.30.80.125

The IP address of a Windows host computer can be changed under:

- Control Panel -> Network Connections -> Local Area Network -> Properties -> Internet Protocol (TCP/IP) -> Properties.

For information on changing the DSA-PTP module’s IP address, see “Changing Boot Parameters (including IP address)” on page 65.

CLIENT/HOST OPTIONS

Once the module has been connected and the IP address has been configured, communications can be established with the DSA-PTP module. Communications can be made through several software packages including:

- PC - TCP/IP
- PC - UDP
- PC - ScanTel (Scanivalve PN: 155406-01)
- PC - LabVIEW Configuration Utility (Scanivalve PN: 155384-01)
- PC - LabVIEW Development Kit (Scanivalve PN: 155385-01)
- PC- DSALink4
- PC - OPC Server
- PC - Windows HyperTerminal

PC - TCP/IP

The user may write their own TCP/IP interface using the software specification portion of this manual. This interface should allow the user to:

- Issue commands to any or all DSA-PTP modules on the network.
- Display returned information or scan data from the DSA-PTP module(s).
- Write returned information or scan data to the client/host in TCP/IP format.
- Determine the addresses of DSA-PTP module(s) on the network.

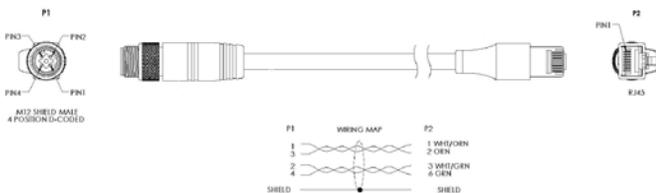


FIGURE 3.2 - 10BASE-T ETHERNET CABLES

PC - UDP

The user may write their own UDP interface using the software specification portion of this manual. This interface should allow the user to:

- Issue commands to any or all DSA-PTP modules on the network.
- Display returned information or scan data from the DSA-PTP module(s).
- Write returned information or scan data to the client/host in UPD format (no handshaking).
- Determine the addresses of DSA-PTP module(s) on the network.

PC - SCANTEL

ScanTel a free communications utility designed by Scanivalve to communicate with Scanivalve products including DSA-PTP modules. It is a text based, command line program that allows users to connect to a single DSA-PTP module and modify the configuration variables, upload or download coefficients and collect data in both TCP/IP and UDP format.

PC - LABVIEW CONFIGURATION UTILITY

The Scanivalve LabVIEW Configuration Utility is software package that offers a very intuitive and simple way to connect to and modify all of the DSA-PTP module's configuration variables. It also allows the user the ability to upload a configuration file and scan and collect data. The scanning and data collection is limited to 5Hz due to the graphic nature of the program. The LabVIEW Configuration Utility is based on a LabVIEW 2009 runtime which is include with the installation disk.

PC - LABVIEW DEVELOPMENT KIT

The Scanivalve LabVIEW Development Kit is for users desiring to customize a LabVIEW driver for DSA-PTP modules. The Development Kit is compatible with LabVIEW 8.2, 8.6 and 2009. The LabVIEW Configuration Utility is included with the Development Kit.

PC - OPC SERVER

Scanivalve has written an OPC Server driver to interface a PC running in an OPC environment with a DSA-PTP module. This program is designed to operate in Windows 2000 or Windows XP.

PC - HYPERTERMINAL

HyperTerminal is a Windows program included as part of Windows 2000, XP and Vista Operating Systems. This program permits a user to connect to a single DSA-PTP module, modify the configuration variables, upload or download coefficients and collect data. HyperTerminal provides a means for both Serial RS-232 and Ethernet connections. It is a text based command line program.

ZERO OFFSET CALIBRATION

The DSA's internal calibration valve incorporates a zero offset correction feature (Quick Zero). This feature provides a simple and quick means to correct for the minor zero drift problem inherent to piezoresistive sensors. Even with pressure applied to the Px ports, the calibration valve can be configured into the 'Quick Zero' calibration mode which pneumatically shorts the positive and the negative side of the reference together. At that point, with the sensor at its natural zero state the offset can be read and recorded. This can then be factored into the engineering units and mathematically removed. All this is done in under 10 seconds with the simple command 'CALZ'. In order for the calibration valve to successfully switch, 90-120 psi of control pressure must be supplied to the 'CTL SUPPLY' port (or just 'CTL' on some DSA3218-PTP modules) and the quick zero jumper must be installed.

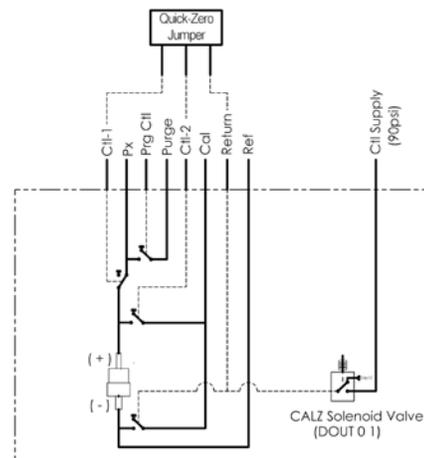


FIGURE 3.3 - QUICK ZERO LOGIC

Absolute pressure modules have a similar zero offset correction feature. The command 'CALB' can be entered followed by the current known barometric pressure to perform a zero offset calibration of absolute pressure modules. More information on both the 'CALZ' and the 'CALB' software commands can be found in "Calibrate Zero" on page 25 and "Calibrate Barometric Pressure" on page 24 respectively.

Due to the nature of the piezoresistive sensors used in the DSA-PTP modules, it is recommended that a 'Quick Zero' be performed at least daily. Performing a 'Quick Zero' more often will not cause any problems and is encouraged. Keep in mind, if the temperature of the module changes more than 3 °C a fresh 'Quick Zero' should be performed.

Zero offset corrections becomes obsolete after several hours or after the module has changed temperatures so all zero offset calibration data is stored in volatile memory and is lost whenever the module power is cycled.

QUICK ZERO JUMPER

In order to perform a zero offset calibration 90-120 psi of control pressure must be individually applied to the CTL1 and the CTL2 control ports. In order to simplify the process, all DSA-PTP modules are shipped with a quick zero jumper. Installing the quick zero jumper to the ‘RTN’, ‘CTL1’ and ‘CTL2’ ports allows the internal calibration valves to be placed into the ‘Quick Zero’ configuration automatically. By simply applying 90-120 psi of control pressure to the ‘CTL SUPPLY’ (or ‘CTL’ on some DSA3218-PTP modules) and calling the ‘CALZ’ or ‘CALB’ command, the DSA-PTP module automatically vents control pressure out of the ‘RTN’ port and to the ‘CTL1’ and ‘CTL2’ ports.

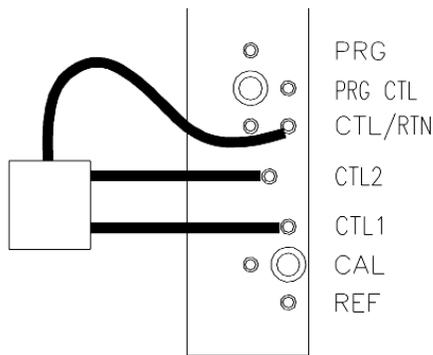


FIGURE 3.4 - QUICK ZERO JUMPER INSTALLATION

SCANNING

Once the DSA-PTP module has been installed, powered up and allowed to thermally stabilize data can be collected. There are several configuration variables that effect how the DSA-PTP module scans and how the data is output. The scan rate is controlled by two variables: ‘period’ and ‘average’ variables, the length of the scan sample is determined by the ‘frames per scan’ (FPS) variable and the data output format is determined by the ‘format’ variable. The DSA-PTP can be configured for ‘free run’ mode where after the ‘SCAN’ command is send the DSA-PTP module will scan continuously until the frames per scan (FPS) term is met, or it can be triggered to scan and output data upon receipt of a scan trigger (either external or a software trigger). The following is a list of commands that effect how the DSA-PTP collects data.

| | |
|---------|-----------|
| AVG | PAGE |
| BIN | PERIOD |
| CVTUNIT | TIME |
| EU | UNITSCAN |
| FORMAT | XSCANTRIG |
| FPS | ZC |

More information on all of these configuration variables can be found in “Section 5: Software” on page 21.

To initiate scanning, simply send the command: ‘SCAN’. If a scan trigger is not being used, data will begin to be output from the DSA-PTP module over the Ethernet connection. This data can be collected and recorded using one of the described in “Client/Host Options” on page 13. If a scan trigger is being used, after the ‘SCAN’ command is sent one frame of data will be output each time a scan trigger is received.

SCANNING WITH AN EXTERNAL TRIGGER

The DSA-PTP module can be triggered to scan with either a hardware or a software trigger.

HARDWARE TRIGGER

The external trigger input is optically isolated to prevent grounding problems. It is a TTL level, edge sensing device. It requires a minimum signal of 4.5Vdc @ 6.5mA. It will accept voltages as high as 15Vdc. The external trigger will only be active if the XSCANTRIG variable is set to 1. When a ‘SCAN’ command is issued through the Ethernet connection, the module enters the scan mode and waits for a trigger. This module will return an averaged frame of data for each trigger pulse received. This will continue until the Frames Per Scan (FPS) term is met or until a ‘STOP’ command is issued. Trigger pulses are received through pins 1 (+Trig) and 2 (-Trig) of the ‘Serial Communications/Trigger’ connector on the front of the DSA-PTP module. More information on the ‘Serial Communications/Trigger’ connection can be found in “Serial Communications” on page 12.

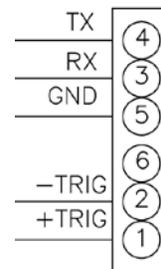


FIGURE 3.5 - TRIGGER WIRING

SOFTWARE TRIGGER

The software trigger will only be active if the software variable XSCANTRIG is set to 1. When a SCAN command is issued through the Ethernet connection, the module will enter the SCAN mode and wait for a trigger. An averaged frame of data will be output as soon as the TRIG command or a <TAB> character (9 HEX or Control I) is received. Data will be output with each successive trigger command. This will continue until the Frames Per Scan (FPS) variable value is met, or until a STOP command is issued.

PURGING

All DSA-PTP modules incorporate an internal calibration valve. One of the configurations of this valve allows for an 'isolate-purge' feature. This permits the pressure measurement (Px) lines to be purged with pressures 50psi over the full scale module pressure up to 500psi during test. If the module range is greater than 500psi it is not recommended to purge during test. It is not recommended to purge at greater than 100psi when purging to atmosphere. This is a very useful feature when the DSA-PTP module is used in applications where corrosive gasses or moisture may be present in the input lines. By isolating the pressure sensors from the purge pressure, even low pressure DSA-PTP modules can be purged safely with high purge pressures.

In order to configure the DSA-PTP module for purge mode 90-120 psi of control pressure must be applied to the 'CTL1' 'CTL2' and 'PRG' ports. **The purge mode must be established in a set order in order to protect the sensor and calibration modules from damage.**

Configuring for purging:

1. Set the calibration valve for calibration mode by applying 90-120 psi of control pressure to both the 'CTL1' and 'CTL2' ports.
2. Apply 90-120 psi of control pressure to the 'CTLPRG' port.
3. Apply the purge pressure to the 'PRG' port.

Re-configuring after a purge:

1. Shut off the purge pressure feeding the 'PRG' port. Make sure to allow sufficient time for the input lines to stabilize. The specific time required will depend upon the physical layout and characteristics of the system.
2. Remove 90-120 psi control pressure from the 'CTLPRG' port.
3. Remove the 90-120 psi control pressure from the 'CTL1 and 'CTL2' ports.



CAUTION

CAUTION! Failing to follow the above procedure while entering or exiting the purge mode could allow the sensor to see the high purge pressure and could seriously damage the DSA-PTP module

FREON APPLICATION OPERATIONS

When using DSA3218-PTP modules in Freon Applications special considerations must be taken. In order to prevent premature deformation of the seals within the DSA3218-PTP's valve, it is important to leave the module in the following 'dormant' state.

- Apply CTL2 and PRGCTL pressures
- Ensure no Px pressures are applied
- Freon present must be vaporized

Any time the module will be left inactive for a significant period of time it should be left in this state. Adhering to this procedure will help ensure long life and prevent any premature maintenance requirements.

SECTION 4: HARDWARE

PNEUMATIC CONNECTIONS

The DSA-PTP module has several different pneumatic connections on the top of the module. There are two basic types of pneumatic connections on each module: pressure measurement connections (Px) and configuration pressure connections (Control). The pressure measurement ports are the 16 ports labeled 1-16 (or 1 through 8 and (-)1 through (-)8 on differential pressure modules) on the top of the module. These ports are connected to the pressure transducers within the module. Also included in the pressure measurement ports are the CAL and REF ports. Dual range modules will have CAL A and CAL B, and REF A and REF B ports. These ports are used for applying known pressures during calibration, and reference pressures during normal data collection and calibrations. It is very important that all pressure measurement connects are completely leak tight. Any minor leak will cause an error in the measured pressure.

The control ports are the remaining ports on the top of the DSA-PTP module. These ports are used for configuring the module and for purging clean air through the module. All air supplied to the control ports needs to be instrument grade, clean dry air. Nitrogen is a very good alternative for when instrument grade air is not available.

All pneumatic connections on the DSA3217-PTP module are 1/16" (1.6mm) stainless steel bulged tubulations. All pneumatic connection on the DSA3218-PTP are 1/8" Swagelok® compression fittings. As an option, 1/16" or 1/4" Swagelok® are available.

MAKING 1/16" TUBULATION CONNECTIONS

Begin by applying a small amount of Scanivalve brown pipe sealant to the outside of the tubulation. Carefully slide the tubing over the outside of the stainless steel tubulation (Scanivalve's tubing push-on tool TPOTL-XXX makes this job easy). Ensure that the end of the Urethane, Nylon or Teflon tubing extends at least 1/16" beyond the bulge on the tubulation. Finally, slide the helical spring clamp over the outside of the tubing, ensuring that the spring clamp ends up over the bulge. Helical spring clamps are required for all pressure ports that will see over 50psi and they are highly recommended for all tubulation style pneumatic connections. When using Teflon tubing, spring clamps are required on all connections no matter what the measurement pressure is.

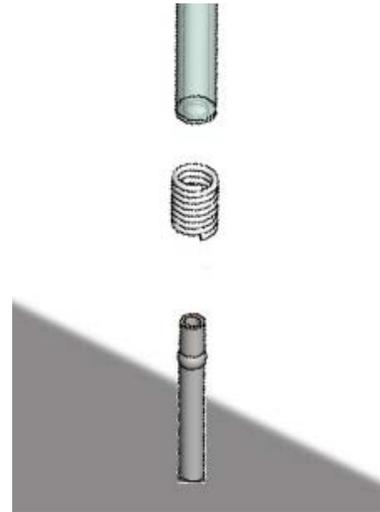


FIGURE 4.1 - TUBULATION PNEUMATIC CONNECTIONS

MAKING SWAGELOK® COMPRESSION CONNECTIONS

Each Swagelok® compression fitting includes 4 parts: the nut, the front ferrule, the back ferrule and the body. Squarely cut the end of the nylon or Teflon tubing being used. Slide the nut and both ferrules up on the tubing, then insert it all of the way into the Swagelok® body. Tighten the nut finger tight, to the point where the tube cannot be removed by hand. Finally, with a wrench tighten the nut 3/4 to 1 1/4 more turns. There is no need to tighten the nut any more than this.

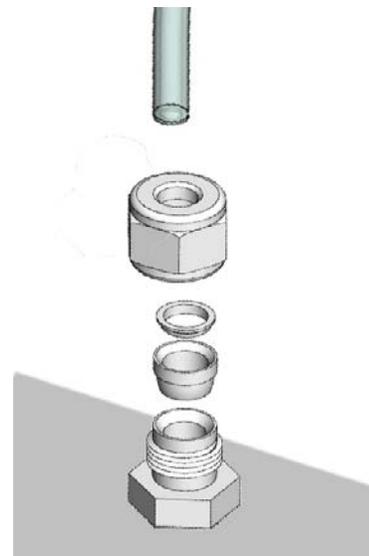


FIGURE 4.2 - SWAGELOK® COMPRESSION CONNECTIONS

PRESSURE MEASUREMENT (Px) PORTS

Each DSA-PTP module has 16 pressure measurement ports, or Px ports. They will be labeled 1-16, or for dual range units $\pm 1-8$. Each of these ports are connected to a discrete pressure transducer. If any Px ports are not being used, it is recommended that they be plugged to prevent dust or debris from clogging the port or contaminating the internal calibration valve.

CALIBRATION (CAL) PORT

For each pressure range the DSA-PTP module has, there will be a 'CAL' port. Most modules will only have one 'CAL' port, but dual range modules will have two (labeled 'CAL' and 'CAL B'). The 'CAL' port provides a means to apply a known calibration pressure to a single port and have it manifolded to all of the transducers of the related pressure range. During normal operations, with no control pressures applied this port is internally blocked off. Any pressure applied to the 'CAL' port will not reach the transducers unless the internal calibration valve has been configured to direct the calibration pressure to the transducers. For low pressure modules (below 5 psi) the 'CAL' port should be routed to a known, stable static location when not being used to apply calibration pressures. This ensures that when a zero offset calibration (CALZ) is performed no unwanted offsets are introduced.

REFERENCE (REF) PORT

For each pressure range the DSA-PTP module has, there will be a 'REF' port. Most modules will only have one 'REF' port, but dual range modules will have two (labeled 'REF' and 'REF B'). On differential pressure modules, the 'REF' port is labeled 'CAL REF'. There is no 'REF' port on absolute or individual reference pressure modules. The 'REF' port ties into a manifold that connects the back side (or negative side) or all transducers of the same pressure range together. During most applications, the 'REF' port of low pressure modules (below 5 psi) should be routed to a known, stable static location. This ensures that when a zero offset calibration (CALZ) is performed no unwanted offsets are introduced. During a calibration, positive pressures will be applied through the 'REF' port to perform the negative portion of the calibration.

CONTROL 1 (CTL1) PORT

Control 1 (CTL1) is the 'isolation' control. Applying 90-120 psi to the CTL1 port closes a normally open (flow) valve and configures the internal calibration valves into isolate mode, meaning that pressures applied to the pressure measurement ports (Px 1-16) will not reach the transducers. CTL1 controls both internal calibration valves simultaneously, they cannot be operated separately. Ensure that any control air applied to CTL1 is clean, dry instrument grade air or nitrogen.

CONTROL 2 (CTL2) PORT

Control 2 (CTL2) is the 'calibration' control. Applying 90-120 psi to the CTL2 port opens a normally closed (no flow) valve and configured the internal calibration valve into calibration mode, meaning that pressures applied to the 'CAL' port(s) will reach the transducers. CTL2 controls both internal calibration valves simultaneously, they cannot be operated separately. Ensure that any control air applied to CTL2 is clean, dry instrument grade air or nitrogen.

CONTROL SUPPLY (CTL SUPPLY OR CTL)

The Control Supply port (CTL SUPPLY on DSA3217-PTP, CTL on DSA3218-PTP) is only required when the quick zero jumper is being used. In this case, 90-120 psi is applied to the CTL Supply port and through the quick zero jumper is directed to the CTL1 and CTL2 ports to put the DSA-PTP module into zero offset calibration (CALZ) mode. This allows the user to remotely perform zero offset calibration (CALZ) as long as 90-120 psi is supplied to the CTL Supply port. For more information on the quick zero jumper, reference "Quick Zero Jumper" on page 15.

RETURN (RTN) PORT

Like the Control Supply port, the Return (RTN) port is only required when using the quick zero jumper. 90-120 psi control air that is supplied through the Control Supply port is switched internally within the module, and when commanded returned out of the Return port to be used to put the module into zero offset calibration (CALZ) mode. For this to function correctly, the quick zero jumper must be installed between the Return (RTN), Control 1 (CTL1) and Control 2 (CTL2) ports. For more detailed information on the quick zero jumper, reference "Quick Zero Jumper" on page 15

PURGE CONTROL (PRGCTL) PORT

For applications where the pressure measurement ports (Px ports) may become plugged or contaminated, the DSA-PTP module is equipped with a purge function. Applying 90-120 psi to the purge control (PRGCTL) port and the control 1 port (CTL1) places the internal calibration valve into purge mode by opening the purge supply to the Px ports and isolating the sensors from the purge pressure. Like the other control pressures, ensure that any control air applied is clean, dry instrument grade air or nitrogen.



CAUTION! Applying PRGCTL after or without CTL1 applied can allow sensors to see the purge pressure potentially causing serious damage to the module.

PURGE SUPPLY (PRG) PORT

The purge supply (PRG) port is the input for the pressure that will be used to purge the pressure measurement (Px) lines. The supplied purge pressure can be up to 750 psi, and must always be clean, dry instrument grade air or nitrogen.

POWER REQUIREMENTS

The DSA3217-PTP requires 28 ±8Vdc at approximately 8 W. This will remain constant while the module is operating normally. The DSA3218-PTP requires 28 ±8Vdc at approximately 8 W. The power requirements for these modules increase to 28 ±8Vdc at approximately 35W if the optional heater is installed. The power requirements will drop when the module reaches the normal operating temperature. If the module is used in an environment where the ambient temperature is 0°C or less, power requirements could remain high.

The power connection is made through a three pin Amphe-nol PTO2A-8-3P connector located on the end of the module.

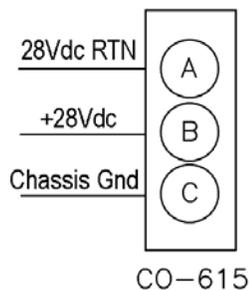


FIGURE 4.3 - POWER WIRING

CALIBRATION VALVE

Each DSA-PTP module has two internal calibration valves. The calibration valves can be configured using the three control pressure inputs on the DSA-PTP module (CTL1, CTL2 and CLTPRG). The two calibration valves cannot be operated independently. The calibration valves are configured such that no control pressures are required for normal measurement operations. The following tables outline the required control pressure input for each calibration valve configuration.

Standard DSA-PTP Calibration Valve configurations:

| MODE | CTL1 | CTL2 | CLT* | PRGCTL |
|------------|------------|------------|------------|------------|
| OPERATE | | | | |
| CALIBRATE | 90-120 psi | 90-120 psi | | |
| QUICK ZERO | 90-120 psi | 90-120 psi | 90-120 psi | |
| PURGE | 90-120 psi | 90-120 psi | | 90-120 psi |
| ISOLATE | 90-120 psi | | | |

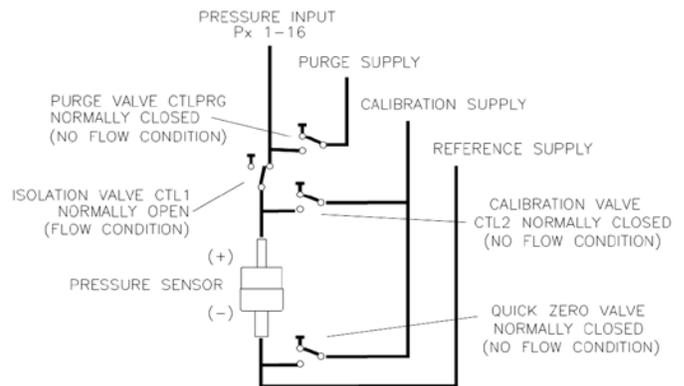


FIGURE 4.4 - STANDARD VALVE LOGIC

Absolute DSA-PTP Calibration Valve configurations:

| MODE | CTL1 | CTL2 | PRGCTL |
|-----------|------------|------------|------------|
| OPERATE | | | |
| CALIBRATE | 90-120 psi | 90-120 psi | |
| PURGE | 90-120 psi | 90-120 psi | 90-120 psi |
| ISOLATE | 90-120 psi | | |

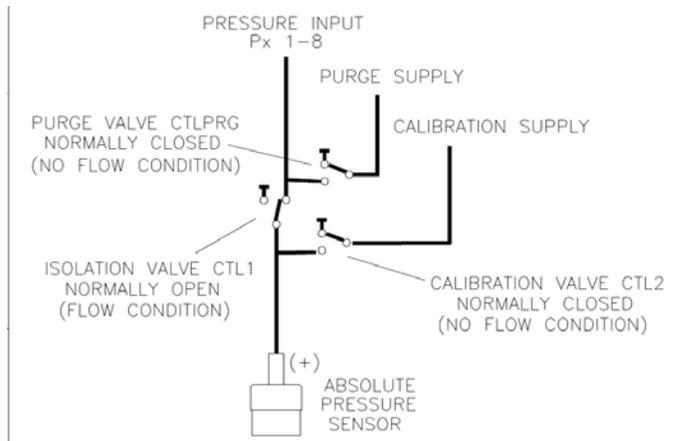


FIGURE 4.5 - ABSOLUTE VALVE LOGIC

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SECTION 5: SOFTWARE

DSA-PTP CONTROL AND CONFIGURATION

The operation of a DSA-PTP module is controlled by sending commands to units selected by network addressing via the network. The DSA-PTP returns any data or information over the network to the requesting client/host.

The section on DSA-PTP Commands lists each command and explains its function.

DSA-PTP COMMANDS

The DSA-PTP software must run as embedded software on the DSA-PTP pressure scanner hardware. It performs the following general tasks:

1. Read and filter the raw A/D counts that represent pressure and temperature.
2. Convert the pressure A/D counts to user chosen pressure units.
3. Receive and execute commands from the Ethernet Link.
4. Allow the configuration to be saved through power down.
5. Output converted data, status, setup and calibration data over the Ethernet Link.
6. Set the DSA-PTP Physical Ethernet Address(MAC Address).
7. Protocol to be TCP/IP or User Defined Protocol.
8. Support the user in troubleshooting the DSA-PTP hardware and system.

TCP/IP does not guarantee that packet boundaries will be maintained between a host and a DSA-PTP module. Therefore, all commands from a host must be terminated properly with one of four options. The DSA-PTP will detect and adjust to the termination option being used by a host.

The four options are:

- CR (ASCII 13)
- LF (ASCII 10)
- LF-CR (ASCII 10 - ASCII 13)
- CR-LF (ASCII 13 - ASCII 10)

The current DSA-PTP RS232 interface includes error checking. A checksum byte is generated and added to the end of the serial data packet. It is assumed that data will be transmitted in ASCII format. Data may be transmitted in BINARY format. If data are to be transmitted in BINARY format, then page mode transmission must be disabled.

Prior to version 1.08, the software would not attempt to output data if the sensor temperatures were less than 0 degrees C. Version 1.08 allows data output at temperatures below 0 °C. In this case, the EU conversion will use the last good set of coefficients. No errors will be logged. If this condition might exist, a user must monitor the sensor temperatures in the data output.

When a DSA-PTP module is in a “not ready” mode, all commands are disabled except STATUS and STOP. Examples of when the DSA-PTP module may be in a “not ready” state could be:

- During CALZ
- During SAVE
- While Scanning

COMMAND LIST**CALCTEMP**

| | |
|----------------|---|
| Command | CALCTEMP |
| Command Syntax | CALCTEMP <channel> |
| Arguments | <channel> - channel number 0 through 15 |
| Description | Calculates the M and B terms for each temperature segments for a given channel |
| Returns | The return format is: Temp Tables Chan <channel> Mndx <M index> Bndx <B index> Pts <number of points> Temp Pt Chan <channel> Pt <point ID> Tmp <temp> Cnts <counts> M <m term> B <B term> ::: ::: ::: ::: ::: ::: ::: ::: ::: Temp Pt Chan <channel> Pt <point ID> Tmp <temp> Cnts <counts> M <m term> B <B term> |
| Example | To calculate and list the temperature terms for channel 1: Type: CALCTEMP 1<Enter> The DSA-PTP will return: Temp Tables Chan 1 Mndx 0.000233 Bndx 3.808413 Pts 9 Temp Pt Chan 1 Pt 0 Tmp 0.100000 Cnts -16320 M 0.002363 B 38.661304 Temp Pt Chan 1 Pt 1 Tmp 9.100000 Cnts -12511 M 0.002230 B 37.000858 Temp Pt Chan 1 Pt 2 Tmp 17.900000 Cnts -8565 M 0.002214 B 36.859257 Temp Pt Chan 1 Pt 3 Tmp 27.000000 Cnts -4454 M 0.002071 B 36.225182 Temp Pt Chan 1 Pt 4 Tmp 35.900002 Cnts -157 M 0.002112 B 36.231590 Temp Pt Chan 1 Pt 5 Tmp 45.099998 Cnts 4199 M 0.001983 B 36.772320 Temp Pt Chan 1 Pt 6 Tmp 54.099998 Cnts 8737 M 0.001944 B 37.114563 Temp Pt Chan 1 Pt 7 Tmp 63.000000 Cnts 13315 M 0.001937 B 37.212395 Temp Pt Chan 1 Pt 8 Tmp 72.000000 Cnts 17962 M 0.001937 B 37.212395 |

CALIBRATE

| | |
|----------------|---|
| Command | CALIBRATE |
| Command Syntax | CAL <press> [group] |
| Arguments | <p><press> - is a real number that represents the calibration pressure for this point.</p> <p>[group] - is a switch that determines the number of channels to calibrate. Group may be H, L or blank. L - Channels 0 - 7(ports 1-8)will be calibrated. H - Channels 8 - 15(ports 9-16) will be calibrated Blank - Channels 0 - 15(ports 1-16) will be calibrated.</p> |
| Description | <p>Commands the DSA-PTP to perform the following:</p> <ol style="list-style-type: none"> 1. Read one averaged frame of pressure and temperature counts. 2. Return calibration information for all channels calibrated in the following format: INSERT <temp> <chan> <press> <press counts>/M <p>NOTE: The DSA-PTP does not control the calibration. It will only read the information when commanded. The User must:</p> <ol style="list-style-type: none"> 1. Apply the control pressures to switch the calibration valves to the CAL mode. 2. Apply a known calibration pressure. 3. Issue the CAL command when the calibration pressure is stable. |
| Returns | <p>INSERT <temp><channel><press><press counts> M<nl></p> <p><temp> - the temperature plane <channels> - the channel in module-port notation <press> - the pressure in EU <press counts> - the A/D pressure counts(or bits) <nl> - end of line</p> |
| Example | <p>If a user wanted to calibrate ports 1 through 8 at 15 psi: Connect a pressure standard to the CAL input. Apply CTL1 and CTL2 Control pressures Enter the command: CAL 15 L<CR></p> <p>The DSA-PTP will measure the counts for each channel and return the appropriate INSERT commands.</p> <p>If a user wanted to calibrate all ports at 15 psi: Connect a pressure standard to the CAL input. Apply CTL1 and CTL2 Control pressures Enter the command: CAL 15<CR></p> <p>The DSA-PTP will measure the counts for each channel and return the appropriate INSERT commands.</p> |

CALIBRATE BAROMETRIC PRESSURE

| | |
|----------------|---|
| Command | CALIBRATE BAROMETRIC PRESSURE |
| Command Syntax | CALB <press> [period] [average] |
| Arguments | <p><press> - is a real number that represents the local barometric pressure.</p> <p>[period] - optional: sets the period for the CALB routine. If this value is not entered, the default period will be 300 microseconds.</p> <p>[average] - optional: sets the average for the CALB routine. If this value is not entered, the default average will be 64.</p> |
| Description | <p>Commands the DSA-PTP to perform the following:</p> <ol style="list-style-type: none"> 1. Read the current counts and enter them in the zero array (list z) 2. Lookup the counts for the pressure entered at the current temperature 3. Subtract the pressure from the zero pressure and enter the difference in the delta array (LIST D) <p>NOTE: In order for the correction to be active, ZC must be set to 1.</p> <p>The CALB function only uses the entered pressure for channels that are defined as absolute sensors (ABS(x) = 1). If a channel is not defined as an absolute channel, the software will perform a CALZ on that channel.</p> <p>The pressure entered as the barometric pressure must be in the units defined in CVTUNIT (i.e.: PSI, kPa, etc)</p> <p>NOTE: The optional period may be the only optional parameter entered. If the optional average is entered, the optional period must be entered.</p> |
| Returns | <nl> - end of line |
| Example | <p>To correct all absolute sensors to read the local barometric pressure:</p> <p>Disconnect all inputs. Enter the command: CALB <press> (Where <press> is the local barometric pressure in the current engineering units.)</p> <p>If CVTUNIT is set to psi, and the local barometric pressure is 14.696 psia,, Enter the command: CALB 14.696</p> <p>If CVTUNIT is set to kPa, and the local barometric pressure is 101.3254, Enter the command: CALB 101.3254</p> |

CALIBRATE ZERO

| | |
|----------------|--|
| Command | CALIBRATE ZERO |
| Command Syntax | CALZ [period] [average] [delay] |
| Arguments | [period] - (optional) sets the period for the CALZ routine. If this value is not entered, the default period will be 300 microseconds. The value entered must be within the limits set for period. [average] - (optional) sets the average for the CALZ routine. If this value is not entered, the default average will be 64. The value entered must be within the limits set for average [delay] - (optional) sets the delay for the CALZ routine. If this value is not entered, the default delay will be 5 seconds. The limits are 5 to 60 seconds |
| Description | Commands the DSA-PTP to perform a quick zero calibration. This operation produces A/D count values for each pressure channel that is subtracted from the raw pressure counts before converting to the chosen pressure units. The data are stored in the ZERO(0-15) and DELTA(0-15) Configuration Variable Array. CALZ requires approximately 15 seconds to complete if the optional parameters are not entered. NOTE: To enter any of the optional parameters, the parameters in the string preceding it must also be entered. For example: To enter a value for average, a value for period must be entered, but not delay. To enter a value for delay, values for both period and average must also be entered. |
| Returns | <nl> <nl> - end of line |
| Example | To update the current ZERO file and correct for any zero drift of the transducers: Enter the command: CALZ The DSA-PTP will measure the zero counts for each channel and update the Zero and Delta Arrays. To update the current ZERO file and correct for any zero drift of the transducers using a period of 500 microseconds and an average of 32: Enter the command: CALZ 500 32 The DSA-PTP will measure the zero counts for each channel and update the Zero and Delta Arrays. To update the current ZERO file and correct for any zero drift of the transducers using a calz delay of 30 seconds and the nominal settings for period and average: Enter the command: CALZ 300 64 30 The DSA-PTP will measure the zero counts for each channel and update the Zero and Delta Arrays. |

CLEAR

| | |
|----------------|--|
| Command | CLEAR |
| Command Syntax | CLEAR |
| Arguments | None |
| Description | Commands the DSA-PTP to clear any errors that have occurred. The errors are sent to the client in an ASCII Packet. ASCII Packets are described in a subsequent sections. |
| Returns | <nl> <nl> - end of line. |
| Example | To clear any errors listed in the ERROR Buffer, the following command would be issued: CLEAR <CR> The ERROR buffer will be cleared |

DELETE

| | |
|----------------|--|
| Command | DELETE |
| Command Syntax | DELETE <start temp><end temp>[<channel>] |
| Arguments | <start temp> - an integer from 0 to 79 that represents the low point of the temperature planes to be deleted. <end temp> - an integer from 0 to 79 that represents the high point of the temperature planes to be deleted. <channel> - (optional) the channel to be deleted. |
| Description | Converts all pressure points within temperature planes between the low and high temperature range, inclusive, to "calculated". This allows new MASTER points to be entered via the CAL command. NOTE: See the description of the FILL command for more information. |
| Returns | <nI> <nI> - end of line. |
| Example | To delete the master points for all modules in a system using eight 32 channel modules, the following command would be issued: DELETE 0 79<CR> To delete the master points for channel 4, the following command would be issued: DELETE 0 79 4<CR> To delete the master points for channel 16, the following command would be issued: DELETE 0 79 16<CR> |

ERROR

| | |
|----------------|--|
| Command | ERROR |
| Command Syntax | ERROR |
| Arguments | None |
| Description | |
| Returns | The return format is: ERROR: error |
| Example | To read the contents of the Error Buffer: Type: ERROR<Enter> The DSA-PTP will return the last 30 errors in the format: ERROR: Port not found ERROR: List MI no group number ERROR: Group not between 1 and 8 If no errors have been logged, the DSA-PTP will return: ERROR: No errors |

FILL

| | |
|----------------|--|
| Command | FILL |
| Command Syntax | FILL |
| Arguments | None |
| Description | <p>Fills the Conversion Table with calculated pressure points and temperature planes using the MASTER calibrated points as guides. These “filled” points are marked as CALCULATED. The FILL command NEVER overwrites MASTER points. It does overwrite old points marked as CALCULATED.</p> <p>NOTE: The DELETE command must be used to change points marked as MASTER to CALCULATED before using the FILL command.</p> |
| Returns | <p><nl> <nl> - end of line.</p> |
| Example | <p>In this example, new MASTER points have been loaded and the coefficient table must be completed. Type: FILL<CR></p> |

INSERT

| | |
|----------------|---|
| Command | INSERT |
| Command Syntax | INSERT <temp> <chan> <press> <press counts> [M] |
| Arguments | <p><temp> - an integer from 0 to 79 that represents the temperature in degrees Celsius. <chan> - an integer from 0 to 15 identifying the channel. <press> - a real number that represents the calibration pressure point. <press counts> - a signed integer from 32767 to -32768 that represents the current pressure counts from the sensor. [M] - optional switch that designates the entry as a master conversion point.</p> |
| Description | <p>Inserts one pressure-pressure counts entry into the Conversion Table. If the M option is used this point is entered as a MASTER point. The LIST MASTER and LIST ALL commands download the contents of the conversion table in the format required by this INSERT command.</p> |
| Returns | <p><nl> <nl> - End of line.</p> |
| Example | <p>Although INSERT commands are most often entered from a Module Profile File, they may be entered from a keyboard.</p> <p>The following command will insert a master point at 30 °C for channel 1. The applied pressure is 11.9998 psi, the measured counts are 26376: INSERT 30 1 11.9998 26376 M</p> <p>The following command will insert a master point at 48 °C for channel 16. The applied pressure is 10.9998 psi, the measured counts are 20254: INSERT 48 16 10.9998 20254 M</p> |

LIST ALL

| | |
|----------------|---|
| Command | LIST ALL |
| Command Syntax | LIST A <Start Temp> <End Temp> [Channel] |
| Arguments | <Start Temp> - The lowest temp plane to be returned. <End Temp> - The highest temp plane to be returned. [Channel] - (Optional) may be 0 through 15. |
| Description | Lists all of the master and calculated points in the temperature-pressure correction matrix. The return format is: INSERT <temp> <chan> <press> <pressure counts> <M> |
| Returns | INSERT <temp> <channel> <press> <press counts> <M><nl> INSERT <temp> <channel> <press> <press counts> <M><nl> : : : : INSERT <temp> <channel> <press> <press counts> <M><nl> <temp> - the temperature plane <channel> - the channel in port notation <press> - the pressure in EU <press counts> - the A/D counts of pressure <nl> - end of line. |
| Example | To list all of the coefficients from 16 °C to 20 °C for channel 1 in a module calibrated from 17 °C to 40 °C type: LIST A 17 20 1<CR> The DSA-PTP will return a list of INSERT commands showing the temperature, channel, applied pressure, counts and the type of plane. INSERT 17 1 -45.949100 -26184 M INSERT 17 1 -31.250000 -17763 M INSERT 17 1 -19.969601 -11302 M INSERT 17 1 -6.250000 -3425 M INSERT 17 1 0.000000 162 M INSERT 17 1 19.984600 11636 M INSERT 17 1 25.000000 14523 M INSERT 17 1 35.000000 20281 M INSERT 17 1 45.949100 26586 M :: :: :: :: :: :: INSERT 20 1 -45.949100 -26166 M INSERT 20 1 -31.250000 -17750 M INSERT 20 1 -19.969601 -11292 M INSERT 20 1-1 -6.250000 -3424 M INSERT 20 1-1 0.000000 160 M INSERT 20 1-1 19.984600 11629 M INSERT 20 1-1 25.000000 14514 M INSERT 20 1-1 35.000000 20267 M INSERT 20 1-1 45.949100 26567 M |

LIST ALL RANGES

| | |
|----------------|--|
| Command | LIST ALL RANGES |
| Command Syntax | LIST B |
| Arguments | None |
| Description | Lists the 16 Absolute/Gauge Settings from the ABSn variable. NOTE: This is active only when MODEL is set to 3207. |
| Returns | <p>SET ABS0 <1 or 0> SET ABS1 <1 or 0> SET ABS2 <1 or 0> SET ABS3 <1 or 0> SET ABS4 <1 or 0> SET ABS5 <1 or 0> SET ABS6 <1 or 0> SET ABS7 <1 or 0> SET ABS8 <1 or 0> SET ABS9 <1 or 0> SET ABS10 <1 or 0> SET ABS11 <1 or 0> SET ABS12 <1 or 0> SET ABS13 <1 or 0> SET ABS14 <1 or 0> SET ABS15 <1 or 0></p> |
| Example | <p>The DSA3207 could contain both Absolute and Gauge Transducers. The setting of ABSx defines the transducer type to the software. To display the transducer type defined for each channel in a DSA3207 with Absolute transducers installed in channels 1 - 6 and 13 - 16, and Gauge Transducers installed in channels 7 - 12, type: LIST B<CR></p> <p>The DSA-PTP module will return the following</p> <pre> SET ABS0 1 SET ABS1 1 SET ABS2 1 SET ABS3 1 SET ABS4 1 SET ABS5 1 SET ABS6 0 SET ABS7 0 SET ABS8 0 SET ABS9 0 SET ABS10 0 SET ABS11 0 SET ABS12 1 SET ABS13 1 SET ABS14 1 SET ABS15 1 </pre> |

LIST CALIBRATE

| | |
|----------------|---|
| Command | LIST CALIBRATE |
| Command Syntax | LIST C |
| Arguments | None |
| Description | Lists the CALIBRATION configuration variables. |
| Returns | SET PMAXL<press> SET PMAXH <press> SET PMINL <press> SET PMINH <press> SET NEGPTSL <num points> SET NEGPTSH <num points> |
| Example | To view the current conversion variable settings, type: LIST C<CR> The DSA-PTP will return the current conversion settings. They could appear as follows. SET PMAXL 18.09 SET PMAXH 18.09 SET PMINL -18.09 SET PMINH -18.09 SET NEGPTSL 4 SET NEGPTSH 4 SET ABS 0 |

LIST DELTA

| | |
|----------------|---|
| Command | LIST DELTA |
| Command Syntax | LIST D |
| Arguments | None |
| Description | Lists the 16 delta zero correction values. These are used in the conversion of raw counts to Engineering Units(EU). |
| Returns | SET DELTA0 <delta> SET DELTA1 <delta> :: :: :: SET DELTA14 <delta> SET DELTA15 <delta> |
| Example | To view the current delta zero correction values, type: LIST D<CR> The DSA-PTP will return the delta zero correction values. They could appear as follows: SET DELTA0 0.00000 SET DELTA1 -0.00243 SET DELTA2 0.00019 SET DELTA3 0.00000 :: :: :: SET DELTA12 -0.00005 SET DELTA13 0.00000 SET DELTA14 0.00009 SET DELTA15 0.00042 NOTE: The delta values will vary as the module ages. These values are the difference between the current zero offset value obtained in the most recent CALZ and the zero value in the coefficient table. |

DIGITAL OUTPUT

| | |
|----------------|---|
| Command | DIGITAL OUTPUT |
| Command Syntax | DOUT <Number> <Value> |
| Arguments | <Number> - The digital output channel 0 through 5 <Value> - 1 = On 0 = Off |
| Description | Commands the DSA-PTP to energize or de-energize a Digital Output Channel. |
| Returns | <nl> <nl> - end of line. |
| Example | To energize Digital Output 1, type: DOUT 1 1<CR> To de-energize Digital Output 5, type: DOUT 5 0<CR> |

LIST FTP SETTINGS (LIST FTP)

| | |
|----------------|---|
| Command | LIST FTP Variables |
| Command Syntax | Returns all of the FTP settings |
| Arguments | LIST FTP |
| Description | All of the FTP setting followed by the prompt. |
| Returns | LIST FTP <i>SET USERFTP Scanivalve</i> <i>SET PASSFTP password</i> <i>SET PATHFTP C:/FTPDIR</i> <i>SET IPFTP 10.0.1.222</i> <i>SET FILEFTP Scan</i> |

LIST GAIN

| | |
|----------------|---|
| Command | LIST GAIN |
| Command Syntax | LIST G |
| Arguments | None |
| Description | Lists the 16 temperature gains. These are used to convert temperature counts to degrees Celsius. This is the “M” term in the characterization equation: $EC = \frac{Counts \& Temp B}{Temp M}$ |
| Returns | SET TEMPM0 <term> SET TEMPM1 <term> SET TEMPM2 <term> :: :: :: SET TEMPM13 <term> SET TEMPM14 <term> SET TEMPM15 <term> |
| Example | To view the temperature gain settings, type: LIST G<CR> The DSA-PTP will return the temperature gain settings. They could appear as follows. SET TEMPM0 793.000000 SET TEMPM1 432.000000 SET TEMPM2 441.000000 :: :: :: SET TEMPM13 412.000000 SET TEMPM14 422.000000 SET TEMPM15 432.000000 NOTE: The temperature gain settings are determined when the sensor is manufactured. They normally will not change after a calibration |

LIST IDENTIFICATION

| | |
|----------------|---|
| Command | LIST IDENTIFICATION |
| Command Syntax | LIST I |
| Arguments | None |
| Description | Lists the IDENTIFICATION configuration variables. |
| Returns | SET ECHO <term> SET MODEL <term> SET PORT <term> SET HOST <term> |
| Example | To verify the general module configuration settings of, type: LIST i<CR> The DSA3217-PTP may return: SET ECHO 0 SET MODEL 3217 SET PORT 23 SET HOST 0.0.0.0 T NOTE: A user must be very careful when modifying one of these variables. An incorrect value in one of these variables could have a detrimental affect on the operation of the module. |

LIST IP SETTINGS (LIST IP)

| | |
|----------------|---|
| Command | LIST IP Variables |
| Command Syntax | Returns all of the IP settings |
| Arguments | LIST IP |
| Description | All of the IP setting followed by the prompt. |
| Returns | <p>LIST IP SET IPADD 191.30.82.100 SET SUBNET 255.255.0.0 SET MAC 000.096.093.082.000.100 SET LOGIN Scanivalve SET PASSWORD Scanner SET LOGIN1 Scanivalve1 SET PASSWORD1 Scanner1 SET ALLOWANON 1 SET APP Dsaptp.hex SET GW 0.0.0.0</p> <p><i>NOTE1: Modifications to the variables in this group may result in one or more of the following conditions:</i></p> <ol style="list-style-type: none"> 1. Unstable network operation. 2. Problems completing FTP file transfers. 3. DSA operational problems <p><i>NOTE2: The variables in this group are not saved when a SAVE command is issued. They may only be saved by using the SAVEIP command.</i></p> |

LIST MASTER

| | |
|----------------|---|
| Command | LIST MASTER |
| Command Syntax | LIST M <Start Temp> <End Temp> [Channel] |
| Arguments | <Start Temp> - The lowest temp plane to be returned. <End Temp> - The highest temp plane to be returned. [Channel] - (Optional) may be 0 through 15. |
| Description | Lists all of the MASTER POINTS in the temperature-pressure correction matrix. The return format is: INSERT <temp> <clear> <pressure> <pressure counts> M |
| Returns | INSERT <temp> <channel> <press> <press counts> M<nl> : : : : INSERT <temp> <channel> <press> <press counts> M<nl> <temp> - the temperature plane <channel> - The channel in module-port or serial number-port notation <press> - the pressure in EU <press counts> - the A/D counts of pressure <nl> - end of line |
| Example | To view the Master Points between 10 °C and 40 °C for channel 1 of the module, type: List m 10 40 1<CR> The DSA-PTP will return: INSERT 14 1 -5.958100 -21594 M INSERT 14 1 -4.476100 -15127 M INSERT 14 1 -2.994200 -8646 M INSERT 14 1 -1.470100 -1973 M INSERT 14 1 0.000000 4467 M INSERT 14 1 1.470100 10917 M INSERT 14 1 2.994200 17594 M INSERT 14 1 4.476100 24098 M INSERT 14 1 5.958100 30603 M INSERT 23 1 -5.958100 -21601 M INSERT 23 1 -4.476100 -15161 M INSERT 23 1 -2.994300 -8714 M INSERT 23 1 -1.470100 -2077 M INSERT 23 1 0.000000 4332 M INSERT 23 1 1.470100 10746 M INSERT 23 1 2.994200 17397 M INSERT 23 1 4.476100 23863 M INSERT 23 1 5.958100 30333 M INSERT 32 1 -5.958100 -21636 M INSERT 32 1 -4.476100 -15214 M INSERT 32 1 -2.994200 -8784 M INSERT 32 1 -1.470100 -2162 M INSERT 32 1 0.000000 4228 M INSERT 32 1 1.470100 10615 M INSERT 32 1 2.994200 17246 M INSERT 32 1 4.476100 23691 M INSERT 32 1 5.958100 30136 M |

LIST MAXn PRESSURES

| | |
|----------------|--|
| Command | LIST MAXn PRESSURES |
| Command Syntax | LIST H |
| Arguments | None |
| Description | Lists the 16 maximum pressures stored in the MAXn Variable. NOTE: This is active only when MODEL is set to 3207. |
| Returns | SET MAX0 <term> SET MAX1 <term> :: :: :: SET MAX14 <term> SET MAX15 <term> |
| Example | To view the maximum pressure settings for the module in the example of List Ranges type: LIST H<CR> The DSA-PTP will return the maximum pressure settings. They could appear as follows: SET MAX0 6.000000 SET MAX1 6.000000 :: :: :: SET MAX14 120.000000 SET MAX15 120.000000 NOTE: Generally, the maximum pressure setting is 20% greater than the full scale of the sensor to allow a user some over range indication. |

LIST MINn PRESSURES

| | |
|----------------|--|
| Command | LIST MAXn PRESSURES |
| Command Syntax | LIST L |
| Arguments | None |
| Description | Lists the 16 maximum pressures stored in the MINn Variable. NOTE: This is active only when MODEL is set to 3207. |
| Returns | SET MIN0 <term> SET MIN1 <term> :: :: :: SET MIN14 <term> SET MIN15 <term> |
| Example | To view the minimum pressure settings for the module in the example of List Ranges type: LIST L<CR> The DSA-PTP will return the minimum pressure settings. They could appear as follows: SET MIN0 -6.000000 SET MIN1 -6.000000 :: :: :: SET MIN13 -120.000000 SET MIN14 -120.000000 NOTE: Generally, the maximum pressure setting is 20% greater than the full scale of the sensor to allow a user some over range indication. |

LIST NEGATIVE POINTS

| | |
|----------------|--|
| Command | LIST NEGATIVE POINTS |
| Command Syntax | LIST N |
| Arguments | None |
| Description | Lists the Negative Points settings for each of the 16 channels in a DSA3207. NOTE: This is active only when MODEL is set to 3207. |
| Returns | <pre>SET NEGPTS0 <term> SET NEGPTS1 <term> SET NEGPTS2 <term> :: :: :: SET NEGPTS13 <term> SET NEGPTS14 <term> SET NEGPTS15 <term></pre> |
| Example | <p>To view the negative points set for the module in the example of List Ranges type: LIST L<CR></p> <p>The DSA-PTP will return the negative points settings. They could appear as follows.</p> <pre>SET NEGPTS0 4 SET NEGPTS1 4 SET NEGPTS2 4 :: :: :: SET NEGPTS13 4 SET NEGPTS14 4 SET NEGPTS15 4</pre> |

LIST OFFSET

| | |
|----------------|---|
| Command | LIST OFFSET |
| Command Syntax | LIST O |
| Arguments | None |
| Description | <p>Lists the 16 temperature offsets. These are used in the conversion of temperature counts to degrees Celsius. This is the "B" term in the correction equation:</p> $EC' \frac{Counts \& TempB}{TempM}$ |
| Returns | <pre>SET TEMPB0 <term> SET TEMPB1 <term> :: :: :: SET TEMPB14 <term> SET TEMPB15 <term></pre> |
| Example | <p>To view the temperature offset settings. type: LIST O<CR></p> <p>The DSA-PTP will return the temperature offset settings. They could appear as follows.</p> <pre>SET TEMPB0 -14121. SET TEMPB1 -10631. :: :: :: SET TEMPB14 -6328. SET TEMPB15 -6156.</pre> <p>NOTE: The temperature offset settings are determined when the sensor is manufactured. They normally will not change after a calibration</p> |

LIST PTP VARIABLES

| | |
|----------------|---|
| Command | LIST PTP VARIABLES |
| Command Syntax | LIST PTP <CR> |
| Arguments | None |
| Description | Lists the PTP configuration variables from Group PTP. |
| Returns | <pre>SET <variable> <value> <nl> SET <variable> <value> <nl> : : : : SET <variable> <value> <nl></pre> <p>variable - the configuration variable name value - the current setting nl - end of line</p> |
| Example | <p>This command is used to verify the general PTP settings of the DSM4000, type: LIST PTP<CR></p> <p>The DSM4000 will return:</p> <pre>SET PTPEN 0 SET STAT 0 SET SST 0:0:0.00000 SET SSD 1971/1/1 SET UTCOFFSET 00:00:00</pre> |

LIST SCAN

| | |
|----------------|--|
| Command | LIST SCAN |
| Command Syntax | LIST S |
| Arguments | None |
| Description | Lists the SCAN configuration variables |
| Example | <p>This command is used to verify the general scan settings of the DSA, type: LIST S<CR></p> <p>The DSA-PTP will return:</p> <pre>SET PERIOD 200 SET AVG 32 SET FPS 1 SET XSCANTRIG 0 SET FORMAT 0 SET TIME 0 SET EU 1 SET ZC 1 SET BIN 0 SET SIM 0 SET QPKTS 0 SET UNITSCAN PSI SET CVTUNIT 1.000000 SET PAGE 0</pre> |

LIST TEMPERATURE

| | |
|----------------|---|
| Command | LIST TEMPn |
| Command Syntax | LIST TEMP <channel> |
| Arguments | <channel> - channel number 0 through 15 |
| Description | Lists the 11 temperature coefficient terms for a specified channel |
| Example | <p>To view the current temperature coefficients for a channel, type: LIST TEMP <chan><CR> The DSA-PTP will return the temperature coefficients for the channel.. They could appear as follows.</p> <pre> SET TEMP 2 0 0.100000 -17381 SET TEMP 2 1 9.100000 -13551 SET TEMP 2 2 17.900000 -9535 SET TEMP 2 3 27.000000 -5355 SET TEMP 2 4 35.900002 -1040 SET TEMP 2 5 45.099998 3403 SET TEMP 2 6 54.099998 7990 SET TEMP 2 7 63.000000 12625 SET TEMP 2 8 72.000000 17358 SET TEMP 2 9 100.000000 0 SET TEMP 2 10 100.000000 0 SET TEMP 2 11 100.000000 0 </pre> <p>NOTE: any temperature value of 100 degrees or greater is discarded and not used. If no coefficients exist for a given channel, the legacy TEMPM and TEMPB terms will be used.</p> |

LIST ZERO

| | |
|----------------|--|
| Command | LIST ZERO |
| Command Syntax | LIST Z |
| Arguments | None |
| Description | Lists the 16 zero correction values. These are used in the conversion of raw counts to zero corrected counts. |
| Example | <p>To view the current zero correction values, type: LIST Z<CR> The DSA-PTP will return the zero correction values. They could appear as follows.</p> <pre> SET ZERO0 261 SET ZERO1 -86 SET ZERO2 -49 SET ZERO3 -6 SET ZERO4 -20 SET ZERO5 47 SET ZERO6 44 SET ZERO7 23 SET ZERO8 -51 SET ZERO9 47 SET ZERO10 6 SET ZERO11 26 SET ZERO12 53 SET ZERO13 37 SET ZERO14 -57 SET ZERO15 -20 </pre> <p>NOTE: The zero values will be updated after a CALZ.</p> |

SAVE

| | |
|----------------|--|
| Command | SAVE |
| Command Syntax | SAVE |
| Arguments | None |
| Description | Commands the DSA-PTP to save the RAM image of the Non Volatile Memory. Any change to a configuration variable must be followed by a SAVE command if the change is to be permanent. |
| Returns | <nl> <nl> - End of line. |
| Example | To save the current configuration variable settings and conversion coefficients, Type: SAVE<CR> |

SCAN

| | |
|----------------|---|
| Command | SCAN |
| Command Syntax | SCAN |
| Arguments | None |
| Description | Commands the DSA-PTP to scan the pressure sensors and send Scan packets to the client. |
| Example | <p>A scan command is executed with EU set to 1, BIN set to 0, and FORMAT set to 0. Data are scrolled and will be displayed as follows:</p> <pre> Frame # <number> Time <time> <μs or ms> <chan> <press eu> <temp eu> " " " " " " <chan> <press eu> <temp eu> </pre> <p>A scan command is executed with EU set to 0, BIN set to 0, and FORMAT set to 0. Data are scrolled and will be displayed as follows:</p> <pre> Frame # <number> Time <time> <μs or ms> <chan> <press counts> <temp counts> " " " " " " <chan> <press counts> <temp counts> </pre> <p>A scan command is executed with EU set to 1, BIN set to 0, and FORMAT set to 1. Data are scrolled and will be displayed as follows:</p> <pre> Frame = <number> Time = <time> <μs or ms> <chan> <press eu> <chan><press eu> <chan> <press eu> <chan> <press eu> <chan> <press eu> <chan><press eu> <chan> <press eu> <chan> <press eu> <chan> <press eu> <chan><press eu> <chan> <press eu> <chan> <press eu> <chan> <press eu> <chan><press eu> <chan> <press eu> <chan> <press eu> </pre> <p>A scan command is executed with EU set to 0, BIN set to 0, and FORMAT set to 1. Data are scrolled and will be displayed as follows:</p> <pre> Frame = <number> Time = <time> <μs or ms> <chan> <press cts> <chan><press cts> <chan> <press cts> <chan> <press cts> <chan> <press cts> <chan><press cts> <chan> <press cts> <chan> <press cts> <chan> <press cts> <chan><press cts> <chan> <press cts> <chan> <press cts> <chan> <press cts> <chan><press cts> <chan> <press cts> <chan> <press cts> </pre> |

SCAN TRIGGER

| | |
|----------------|--|
| Command | SCAN TRIGGER |
| Command Syntax | TRIG or <tab> |
| Arguments | None |
| Description | This command acts as a software trigger to the DSA. When XSCANTRIG is set to 1, an averaged frame of data will be output when the DSA-PTP receives the TRIG command or a <TAB> character code (9 HEX or Control I). This will continue until a STOP command is issued or the Frames Per Scan (FPS) variable is met. The data format will depend upon the setting of EU, BIN and FORMAT. |
| Example | A scan command is executed with EU set to 1, BIN set to 0, XSCANTRIG set to 1, and FORMAT set to 0. The DSA-PTP will wait for a Hardware trigger, the TRIG command or a <TAB> character (9 HEX or Control I). When one of the Data are scrolled and will be displayed as follows: Frame # <number> Time <time> <μs or ms> <chan> <temp eu> " " " " " " <chan> <temp eu> For information on other formats, refer to the SCAN command . |

SET

| | |
|----------------|---|
| Command | SET |
| Command Syntax | SET <name> <value> |
| Arguments | <name> - the Configuration Variable to be set or modified. <value> - the value of that Configuration Variable |
| Description | Commands the DSA-PTP to set one of the many Configuration Variables. Configuration Variables are described in a subsequent section. NOTE: Listing the Configuration Variables with the LIST command outputs the data in the format required by the SET command. This enables the user to upload data from a file that has been created by a LIST download. |
| Returns | <nl> <nl> - End of line. |
| Example | To change the variable Frames Per Scan (FPS) from 10 to 5, type: SET FPS 5 <CR> To change the variable Time (TIME) from off (0) to on (1), type: SET TIME 1 <CR> |

STATUS

| | |
|----------------|---|
| Command | STATUS |
| Command Syntax | STATUS |
| Arguments | None |
| Description | Commands the DSA-PTP to send a Status Packet to the client. The Status Packet is described in a subsequent section. The STATUS command may be entered at any time. This is one of the commands that will not generate an error if entered while the DSA-PTP is not READY. |
| Returns | One of the following: STATUS: READY STATUS: CALZ STATUS: SAVE |
| Example | If the STATUS command is entered while the DSA-PTP is on, but inactive, the DSA-PTP will return: STATUS: READY If the STATUS command is entered while the DSA-PTP is executing a Calibrate Zero command, the DSA-PTP will return: STATUS CALZ |

STOP

| | |
|----------------|---|
| Command | STOP |
| Command Syntax | STOP or <esc> |
| Arguments | None |
| Description | Commands the DSA-PTP to abort the current operation. |
| Returns | <n> <n> - end of line. |
| Example | To abort any function or operation, type: STOP<CR> |

UPLOAD

| | |
|----------------|--|
| Command | UPLOAD |
| Command Syntax | UPLOAD <S or C><filepath\filename> |
| Arguments | S - System file to be uploaded C - Configuration file to be uploaded |
| Description | Uploads the specified file to the DSA-PTP module. The DSA-PTP interprets the type of file based on the file type argument. |
| Returns | <n> <n> - end of line. |
| Example | To upload the configuration variable file <code>cv.cfg</code> , located in the <code>dsfiles</code> subdirectory on drive <code>c:</code> of the host computer, type: UPLOAD C c:\dsfiles\cv.cfg NOTE: S or C must be uppercase. Refer to "DSA3200-PTP Operating System Upload" on page 68 for more information. |

VERSION

| | |
|----------------|--|
| Command | VERSION |
| Command Syntax | VER |
| Arguments | None |
| Description | Outputs the current software version number. |
| Returns | VERSION: DsaHs Scanivalve © 2000 -2013 Ver <ver number> |
| Example | To read the current software version, type: VER<CR> The DSA-PTP returns: VERSION: DsaHs Scanivalve © 2000 - 2013 Ver 1.17 |

SET PTP TIME

| | |
|----------------|---|
| Command | SETTIME |
| Command Syntax | SETTIME YYYY/MM/DD hh:mm:ss.fff |
| Arguments | YYYY- Year MM- Month DD- Day hh- hour mm- minute ss- seconds fff- fractions of a second |
| Description | Programs the curent time to the DSA |
| Returns | <nl> <nl> - end of line. |

GET PTP TIME

| | |
|----------------|--|
| Command | GETTIME |
| Command Syntax | GETTIME |
| Arguments | None |
| Description | Commands the DSA-PTP to get the PTP time. If no grandmaster is present or time pro-gramed, the MPS will return the default time. Time is adjusted by UTCOFFSET |
| Returns | Current Time YYYY/MM/DD hh:mm:ss.fff sec XXXX ns YYYYYYYYYY |

GET UTC OFFSET

| | |
|----------------|--|
| Command | GETUTCO |
| Command Syntax | GETUTCO |
| Arguments | None |
| Description | Commands the DSA-PTP to get the UTC offset from the grandmaster |
| Returns | - The current difference between TAI time and UTC time, in seconds, as supplied by the local grandmaster. - UTC updated flag - Set when UTC offset is valid. Current UTC Offset 0 0 0 |

CONFIGURATION VARIABLES

Configuration Variables control the way the DSA-PTP functions. The variables are assigned to one of several groups: SCAN (LIST S), CALIBRATION (LIST B, LIST C, LIST H, LIST L, LIST N), IDENTIFICATION (LIST I), IP (LIST IP), FTP (LIST FTP), PTP (LIST PTP) or PRESSURE (LIST D, LIST O, LIST G, and LIST Z). Each variable is assigned a “data type” description.

SCAN VARIABLES (LIST S)**AVERAGE (AVG)**

| | |
|---------------|--|
| Variable | AVG |
| Valid Values | 1 to 240 |
| Default Value | 32 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | This sets the number of raw samples to acquire before producing a averaged output. |

BINARY DATA (BIN)

| | |
|---------------|---|
| Variable | BIN |
| Valid Values | 0 or 1 |
| Default Value | 0 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | Sets the format of the data packet output. 1 = Binary 0 = ASCII |

UNIT CONVERSION FACTOR (CVTUNIT)

| | |
|---------------|---|
| Variable | CVTUNIT |
| Valid Values | any real number |
| Default Value | 1.0 |
| Data Type | float |
| Group | Scan variables (List S) |
| Description | Unit conversion factor. This converts the calibrated units to the requested scan units. This value can be set directly or by setting the UNITSCAN variable to the desired unit. CVTUNIT will be set whenever UNITSCAN is set. It may be set independently without setting UNITSCAN. If a user wants to have CVTUNIT set to a different variable from UNITSCAN, UNITSCAN must be set first. |

ENGINEERING UNITS (EU)

| | |
|---------------|---|
| Variable | EU |
| Valid Values | 0 or 1 |
| Default Value | 1 |
| Data Type | string |
| Group | Scan variables (List S) |
| Description | <p>Sets the output format for temperature and pressure units.</p> <p>0 = raw units 1 = Engineering units</p> <p>NOTE: The module will output 999999 when one or more of the following conditions exist:</p> <ol style="list-style-type: none"> 1. The EU conversion exceeds the setting of PMAXL or PMAXH 2. The calculated temperature of any sensor is greater than 69 degrees C. <p>The module will output -999999 when one or more of the following conditions exist:</p> <ol style="list-style-type: none"> 1. The EU conversion exceeds the setting of PMINL or PMINH 2. The calculated temperature of any sensor is greater than 69 degrees C. |

DATA FORMAT (FORMAT)

| | |
|---------------|---|
| Variable | FORMAT |
| Valid Values | 0, 1, or 2 |
| Default Value | 0 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | <p>Determines if data are to be scrolled on the display. ASCII Output only</p> <p>0 - data are scrolled 1 - data are displayed in place, formatted for a VT100 terminal. 2- data is displayed in CSV format</p> |

FRAMES PER SCAN (FPS)

| | |
|---------------|---|
| Variable | FPS |
| Valid Values | 0 to 2147483648 |
| Default Value | 1 |
| Data Type | long integer |
| Group | Scan variables (List S) |
| Description | <p>Frames Per Scan (FPS) sets the number of averaged frames to send to the host computer when a scan command is issued. Averaged frames will be sent to the host computer until the value of FPS is met. At that time the DSA-PTP will exit the scan mode and wait for another command. If a 0 is entered, the scan will continue until a STOP command is received.</p> |

PAGE (PAGE)

| Variable | PAGE |
|---------------|---|
| Valid Values | 0 or 1 |
| Default Value | 0 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | <p>When set to 1, the DSA-PTP will accumulate 10 frames of data before the data is sent over the network. If FPS is set to a number less than 10, the data will be sent over the network when FPS is completed. When a STOP command is issued, the frame acquisition will stop on a 10 frame boundary.</p> <p>NOTE: This variable is active in UDP mode only.</p> |

PERIOD (PERIOD)

| Variable | PERIOD |
|---------------|--|
| Valid Values | 73.5 to 65535 |
| Default Value | 500 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | <p>Sets the interval between channel samples, in microseconds (μs). Period is related to the scan rate, or frequency by the formula: $\text{Data Rate} = 1 \div (\text{Period} * \times 16 \times \text{Average})$</p> <p>*where period is in seconds</p> |

QPKTS

| Variable | QPKTS |
|---------------|--|
| Valid Values | 0 or 1 |
| Default Value | 0 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | <p>This switch will control the action the DSA-PTP will take when the data buffer is full.</p> <p>0 - frames will be discarded when the data buffer is full. The DSA-PTP will continue to scan.</p> <p>1 - no frames will be lost. The DSA-PTP will stop scanning and log an error if the data buffer is filled.</p> |

DATA SAMPLE SOURCE (SIM)

| Variable | SIM |
|---------------|---|
| Valid Values | 0 or 1 |
| Default Value | 1 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | <p>Determines the source of the data samples.</p> <p>0 - Data are taken from the sensors</p> <p>1 - Data are generated internally</p> |

TIME STAMP (TIME)

| | |
|---------------|---|
| Variable | TIME |
| Valid Values | 0, 1 or 2 |
| Default Value | 0 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | Determines the format of the Time Stamp. 0 - No Time Stamp 1 - Time stamp data are in microseconds 2 - Time stamp data are in milliseconds |

SCAN UNIT (UNITSCAN)

| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|---------------|--|--------|-------|-------|------|-------|-----|------|--------|------|-------|------|------|------|-----|----|-------|-------|-----|------|-----|---------|-------|------|-----|-----|------|--|--|--|--|
| Variable | UNITSCAN | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Valid Values | See list in description | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Default Value | PSI | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Data Type | string | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Group | Scan variables (List S) | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Description | <p>Unit scan factor. This sets the scan units for the DSA. Setting this value will also set CVTUNITS. CVTUNITS may be set to a different value, however UNITSCAN must be set first. The following are the list of units supported</p> <table border="0"> <tr> <td>ATM</td> <td>FTH2O</td> <td>KGM2</td> <td>MH2O</td> <td>OZFT2</td> </tr> <tr> <td>BAR</td> <td>GCM2</td> <td>KIPIN2</td> <td>MMHG</td> <td>OZIN2</td> </tr> <tr> <td>CMHG</td> <td>INHG</td> <td>KNM2</td> <td>MPA</td> <td>PA</td> </tr> <tr> <td>CMH2O</td> <td>INH2O</td> <td>KPA</td> <td>NCM2</td> <td>PSF</td> </tr> <tr> <td>DECIBAR</td> <td>KGCM2</td> <td>MBAR</td> <td>NM2</td> <td>PSI</td> </tr> <tr> <td>TORR</td> <td></td> <td></td> <td></td> <td></td> </tr> </table> <p>If a value other than those listed is entered, PSI will be used. It is best to use uppercase when entering these units.</p> | ATM | FTH2O | KGM2 | MH2O | OZFT2 | BAR | GCM2 | KIPIN2 | MMHG | OZIN2 | CMHG | INHG | KNM2 | MPA | PA | CMH2O | INH2O | KPA | NCM2 | PSF | DECIBAR | KGCM2 | MBAR | NM2 | PSI | TORR | | | | |
| ATM | FTH2O | KGM2 | MH2O | OZFT2 | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| BAR | GCM2 | KIPIN2 | MMHG | OZIN2 | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CMHG | INHG | KNM2 | MPA | PA | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CMH2O | INH2O | KPA | NCM2 | PSF | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| DECIBAR | KGCM2 | MBAR | NM2 | PSI | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| TORR | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

ENABLE EXTERNAL TRIGGER (XSCANTRIG)

| | |
|---------------|---|
| Variable | XSCANTRIG |
| Valid Values | 0 or 1 |
| Default Value | 0 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | Sets the External Trigger as the Frame Trigger. 0 - the internal clock is the frame trigger 1 - the external trigger is the frame trigger |

ZERO CORRECTION (ZC)

| | |
|---------------|---|
| Variable | ZC |
| Valid Values | 0 or 1 |
| Default Value | 1 |
| Data Type | integer |
| Group | Scan variables (List S) |
| Description | <p>Sets zero correction on or off. 0 - no correction 1 - zero correction</p> <p>NOTE 1: ZC must be set to 0 for the following conditions: 1. Model is set to 3207 2. The module has gauge transducers installed.</p> <p>NOTE 2: ZC must be set to 0 for the following conditions: 1. Model is set to 3207 2. Absolute sensors are installed and the CALB command will not be used.</p> <p>NOTE 3: ZC must be set to 1 for the following conditions: 1. Model is set to 3217 or 3218 2. Differential transducers are installed</p> <p>NOTE 4: ZC must be set to 1 for the following conditions: 1. Model is set to 3207 2. Absolute sensors are installed and the CALB command will be used.</p> |

IP VARIABLES (LIST IP)**IP ADDRESS (IPADD)**

| | |
|---------------|-------------------------------|
| Variable | IPADD <IP Address> |
| Valid Values | Any valid IP Address |
| Default Value | determined by module type |
| Data Type | integer |
| Group | IP variables (List IP) |
| Description | The IP Address of the module. |

SUBNET MASK (SUBNET)

| | |
|---------------|---|
| Variable | SUBNET <Subnet Mask> |
| Valid Values | Any valid Subnet Mask |
| Default Value | 255.255.0.0 |
| Data Type | integer |
| Group | IP variables (List IP) |
| Description | The Subnet mask for the module. The subnet mask must be configured for the network where the DSA will be connected. |

MAC ADDRESS (MAC)

| | |
|---------------|---|
| Variable | MAC <MAC Address> |
| Valid Values | 000.096.093.xxx.yyy.zzz |
| Default Value | 000.096.093.040.000.xxx Where xxx is the serial number of the enclosure |
| Data Type | integer |
| Group | IP variables (List IP) |
| Description | The MAC address of the module. The last three octets may be modified by a user, but it is recommended that they not be modified. The first three octets MUST NOT be modified. These octets represent a setting registered to Scanivalve Corp. |

LOGIN (LOGIN)

| | |
|---------------|---------------------------------|
| Variable | LOGIN <User Name> |
| Valid Values | Any valid string |
| Default Value | Scanivalve |
| Data Type | string |
| Group | IP variables (List IP) |
| Description | The User name for the FTP login |

PASSWORD (PASSWORD)

| | |
|---------------|--|
| Variable | PASSWORD <Password> |
| Valid Values | any valid character string |
| Default Value | Scanner |
| Data Type | string |
| Group | IP variables (List IP) |
| Description | The password associated with the user name for the FTP login |

LOGIN 1(LOGIN1)

| | |
|---------------|---------------------------------|
| Variable | LOGIN1 <User Name> |
| Valid Values | any valid character string |
| Default Value | Scanivalve1 |
| Data Type | string |
| Group | IP variables (List IP) |
| Description | The User name for the FTP login |

PASSWORD 1(PASSWORD1)

| | |
|---------------|--|
| Variable | PASSWORD1 <Password> |
| Valid Values | any valid character string |
| Default Value | Scanner1 |
| Data Type | string |
| Group | IP variables (List IP) |
| Description | The password associated with the user name for the FTP login |

ANONYMOUS LOGON (ALLOWANON)

| | |
|---------------|---|
| Variable | ALLOWANON <code> |
| Valid Values | 0 or 1 |
| Default Value | 1 |
| Data Type | integer |
| Group | IP variables (List IP) |
| Description | Allows anonymous users to access DSA memory for firmware and coefficient upload. 0 - Do not allow anonymous FTP logins 1 - Allow anonymous FTP logins (recommended) |

APPLICATION (APP)

| | |
|---------------|---|
| Variable | APP <application name> |
| Valid Values | any valid application name |
| Default Value | Dsaptp.hex |
| Data Type | string |
| Group | IP variables (List IP) |
| Description | The file name of the application to run. This is the file name that is used when automatically running the application from the boot loader. It is also the file name used when using the RUN command. If this file is not found, an error is returned. |

SET GATEWAY (GW)

| | |
|---------------|---|
| Variable | GW <IP Address> |
| Valid Values | any valid IP address |
| Default Value | 0.0.0.0 |
| Data Type | integer |
| Group | IP variables (List IP) |
| Description | This IP Address will be used to access the server if the server IP address is an IP Address outside the DSM subnet. |

PTP VARIABLES (LIST PTP)**PTP ENABLE (PTPEN)**

| | |
|---------------|---|
| Variable | PTPEN <code> |
| Valid Values | 0-disabled, 1-enable, 2-enable as master |
| Default Value | 0 |
| Data Type | integer |
| Group | PTP variables (List PTP) |
| Description | Enables the precision time protocol engine in the DSA-PTP. When PTPEN is set to 2, the DSA-PTP will serve as a PTP master. NOTE: Only one unit may be set to a master. Having multiple masters on the same network may cause some to be ignored. |

PTP STATISTICS (STAT)

| | |
|---------------|--|
| Variable | STAT <code> |
| Valid Values | 0- disable, 1- serial, 2- network |
| Default Value | 0 |
| Data Type | integer |
| Group | PTP variables (List PTP) |
| Description | Sets the destination of PTP statistical output. The statistical data is output in the following format: <ofm>, <msd>, <smd>, <mpd> ofm- Offset From Master. Time that slave and master differ in units of microseconds msd - Master to Slave Delay. Filtered packet delivery time from master to slave smd - Slave to Master Delay. Filtered packet delivery time from slave to master mpd - Mean Path Delay. Filtered mean path delay time |

SCAN START TIME (SST)

| | |
|---------------|---|
| Variable | SST <code> |
| Valid Values | hhh:mmm:ss.fff |
| Default Value | 0:0:0.000 |
| Data Type | integer |
| Group | PTP variables (LIST PTP) |
| Description | Sets the time to start scanning as referenced to the grandmaster or PTP master. The DSA-PTP will use the current PTP time as the scan start time under two conditions: 1) When the PTP system is disabled via the SET PTPEN 0 command. 2) When the current time has not been received from the PTP server since the DSA-PTP was powered up. Under this condition the DSA-PTP time will start at Jan 1 2014, 0:00:00.000 hours, or epoch 0 time. This most likely will happen when there is no PTP server on the network. If the DSA-PTP was enabled and then disabled after receiving a time set from the PTP time server, the DSA-PTP will keep time from the last clock setting from the PTP server. When these two cases are not met, the DSA-PTP uses the start time set via the SET SST <time> and SET SSD <date> setting in the PTP group. |

SCAN START DATE (SSD)

| | |
|---------------|---|
| Variable | SSD <code> |
| Valid Values | yyyy/mm/dd Where: yyyy-Year, mm-Month, dd-Day |
| Default Value | 2014/1/1 |
| Data Type | integer |
| Group | Calibration variables (List B) |
| Description | Sets the date to start scanning as referenced to the grandmaster. |

UTC OFFSET (UTCOFFSET)

| | |
|---------------|--|
| Variable | UTCOFFSET <code> |
| Valid Values | hh:mm:ss Where: hh- Hours, mm- Minutes, ss- Seconds |
| Default Value | 00:00:00 |
| Data Type | integer |
| Group | PTP variables (List PTP) |
| Description | Sets the offset to be added or subtracted from network time. |

FTP VARIABLES (LIST FTP)***FTP USER NAME (UESRFTP)***

| | |
|---------------|--|
| Variable | USERFTP <user name> |
| Valid Values | any valid string |
| Default Value | admin |
| Data Type | string |
| Group | FTP variables (List FTP) |
| Description | Sets the name of the user login on the FTP server or NAS |

FTP PASSWORD (PASSFTP)

| | |
|---------------|---|
| Variable | PASSFTP <password> |
| Valid Values | any valid string |
| Default Value | password |
| Data Type | string |
| Group | FTP variables (List FTP) |
| Description | Sets the name of the user password for login on the FTP server or NAS |

ENABLE FTP (ENFTP)

| | |
|---------------|-----------------------------|
| Variable | ENFTP <code> |
| Valid Values | 0- disabled or 1- enabled |
| Default Value | 0 |
| Data Type | integer |
| Group | FTP variables (List FTP) |
| Description | Enables data output via FTP |

FTP FILE PATH (PATHFTP)

| | |
|---------------|--|
| Variable | PATHFTP <directory path> |
| Valid Values | any valid path |
| Default Value | /disk1/share |
| Data Type | string |
| Group | FTP variables (List FTP) |
| Description | Set the directory path of the scan data file on the user's computer. |

FTP IP ADDRESS(IPFTP)

| | |
|---------------|---|
| Variable | IPFTP <IP Address> |
| Valid Values | any valid IP Address |
| Default Value | 10.0.0.1 |
| Data Type | integer |
| Group | FTP variables (List FTP) |
| Description | Set the IP address of the users FTP server. |

FTP FILE NAME(FILEFTP)

| | |
|---------------|---|
| Variable | FILEFTP <name> |
| Valid Values | any valid string |
| Default Value | SCAN |
| Data Type | string |
| Group | FTP variables (List FTP) |
| Description | Set the base name for the scan data on the user's computer. The actual name will have the time and date appended to the file. It will have a file extension based on the data format. |

PRESSURE VARIABLES (LIST B, LIST H, LIST L AND LIST N)**ABSOLUTE ENABLE (ABS_N)**

| | |
|---------------|---|
| Variable | ABS _n (where n = 0-15 for channels 1-16) |
| Valid Values | 0 or 1 |
| Default Value | determined by module type |
| Data Type | integer |
| Group | Calibration variables (List B) |
| Description | Sets the mode of operation of the module. NOTE: This is active only when MODEL is set to 3207. 0 = gauge or differential 1 = absolute |

MAXIMUM PRESSURE (MAX_N)

| | |
|---------------|--|
| Variable | MAX _n (where n = 0-15 for channels 1-16) |
| Valid Values | 0 through 500 |
| Default Value | 15 |
| Data Type | integer |
| Group | Calibration variables (List H) |
| Description | Sets the maximum pressure for channel n. This variable is only used if MODEL is set to 3207. This must be set to zero or to a positive number if the module is an absolute module. |

MINIMUM PRESSURE (MIN_N)

| | |
|---------------|--|
| Variable | MIN _n (where n = 0-15 for channels 1-16) |
| Valid Values | 0 through 500 |
| Default Value | 0 |
| Data Type | integer |
| Group | Calibration variables (List L) |
| Description | Sets the maximum pressure for channel n. This variable is only used if MODEL is set to 3207. This must be set to zero or to a positive number if the module is an absolute module. |

NEGATIVE CALIBRATION POINTS (NEGPTS_N)

| | |
|---------------|---|
| Variable | NEGPTS _n (where n = 0-15 for channels 1-16) |
| Valid Values | 0 to 8 |
| Default Value | 4 |
| Data Type | integer |
| Group | Calibration variables (List N) |
| Description | Sets the number of negative calibration points for channel n. This must be set to zero or to a positive number if the module is an absolute module. This variable is only used if MODEL is set to 3207. |

CALIBRATION VARIABLES (LIST C)

CHANNEL 1-8 NUMBER OF NEGATIVE CALIBRATION POINTS (NEGPTSL)

| | |
|---------------|--|
| Variable | NEGPTSL |
| Valid Values | 0 through 8 |
| Default Value | 4 |
| Data Type | integer |
| Group | Calibration variables (List C) |
| Description | Sets the number of negative calibration points for channels 1 - 8. This must be set to zero or to a positive number if the module is an absolute module. |

CHANNEL 9-16 NUMBER OF NEGATIVE CALIBRATION POINTS (NEGTPSH)

| | |
|---------------|---|
| Variable | NEGTPSH |
| Valid Values | 0 through 8 |
| Default Value | 4 |
| Data Type | integer |
| Group | Calibration Variables (List C) |
| Description | Sets the number of negative calibration points for channels 9 - 16. This must be set to zero or to a positive number if the module is an absolute module. |

CHANNEL 1-8 MAXIMUM PRESSURE (PMAXL)

| | |
|---------------|---|
| Variable | PMAXL |
| Valid Values | any real number |
| Default Value | determined by module type |
| Data Type | float |
| Group | Calibration variables (List C) |
| Description | Sets the maximum pressure for channels 1 - 8. NOTE: The module will output 999999 if the measured pressure exceeds this value. |

CHANNEL 9-16 MAXIMUM PRESSURE (PMAXH)

| | |
|---------------|--|
| Variable | PMAXH |
| Valid Values | any real number |
| Default Value | determined by module type |
| Data Type | float |
| Group | Calibration variables (List C) |
| Description | Sets the maximum pressure for channels 9 - 16. NOTE: The module will output 999999 if the measured pressure exceeds this value. |

CHANNEL 1-8 MINIMUM PRESSURE (PMINL)

| | |
|---------------|--|
| Variable | PMINL |
| Valid Values | any real number |
| Default Value | determined by module type |
| Data Type | float |
| Group | Calibration Variables (List C) |
| Description | Sets the minimum pressure for channels 1 - 8. This must be set to zero or to a positive number if the module is an absolute module. NOTE: The module will output -999999 if the measured pressure exceeds this value. |

CHANNEL 9-16 MINIMUM PRESSURE (PMINH)

| | |
|---------------|--|
| Variable | PMINH |
| Valid Values | any real number |
| Default Value | determined by module type |
| Data Type | float |
| Group | Calibration Variables (List C) |
| Description | Sets the minimum pressure for channels 9 -16. This must be set to zero or to a positive number if the module is an absolute module. NOTE: The module will output -999999 if the measured pressure exceeds this value. |

IDENTIFICATION VARIABLES (LIST I)

SERIAL ECHO (ECHO)

| | |
|---------------|--|
| Variable | ECHO |
| Valid Values | 0 or 1 |
| Default Value | 0 |
| Data Type | integer |
| Group | Identification variables (List I) |
| Description | Determines if characters received from a serial host will be echoed back to the host. 0 - the DSA-PTP will not echo characters 1 - the DSA-PTP will echo characters back to the host |

MODEL (MODEL)

| | |
|---------------|---|
| Variable | MODEL |
| Valid Values | 3207, 3217, 3218 |
| Default Value | 3217 |
| Data Type | string |
| Group | Identification variables (List I) |
| Description | Determines the module type. When set to 3207, special variables are enabled to permit up to eight(8) ranges in a module. The recommended setting of ZC depends on the setting of MODEL. Please refer to the description of ZC for more information. NOTE: MODEL must be set to 3207 in a 3217 or 3218 with absolute sensors installed if the CALB function will be used. |

ETHERNET PORT (PORT)

| | |
|---------------|---|
| Variable | PORT |
| Valid Values | any valid port other than 0 |
| Default Value | 23 |
| Data Type | integer |
| Group | Identification variables (List I) |
| Description | Sets the Ethernet port. The default value is 23 which is the TelNet port. A change to this variable does not take effect until the module has been rebooted. If PORT is set to zero, communications in Ethernet will be impossible. |

ETHERNET HOST (HOST)

| | |
|---------------|--|
| Variable | HOST <IP Address> <Port> <Protocol> |
| Valid Values | IP Address - Any valid IP Address Port - Any valid port number other than 0 Protocol - U for UDP T for TCP |
| Default Value | IP Address - 0 Port - 0 Protocol - T |
| Data Type | varies |
| Group | Identification variables (List I) |
| Description | Sets the parameters for binary transmission to a host computer. The default port value is 23 which is the TelNet port. A change to this variable does not take effect until the module has been rebooted. If PORT is set to zero, communications in Ethernet will be impossible. |

PRESSURE DELTAS (LIST D)**DELTAS (DELTAN)**

| | |
|---------------|---|
| Variable | DELTAn <value> (where n = 0-15 for channels 1-16) |
| Valid Values | +/- Full Scale Pressure Range |
| Default Value | none |
| Data Type | float |
| Group | Pressure variables (List D) |
| Description | Delta zero corrections for channels 1 - 16. These values are set when a CALZ is executed. |

TEMPERATURE OFFSETS (LIST O)**TEMPERATURE OFFSET (TEMPBN)**

| | |
|---------------|--|
| Variable | TEMPBn (where n = 0-15 for channels 1-16) |
| Valid Values | any real number |
| Default Value | none |
| Data Type | float |
| Group | Pressure variables (List O) |
| Description | The "B" term in the conversion equation used to convert temperature counts to degrees Celsius. The conversion formula is: $EC \frac{Counts \& Temp B}{Temp M}$ <p>This variable is used only as a placeholder for legacy compatibility.</p> |

TEMPERATURE GAINS (LIST G)

TEMPERATURE GAIN (TEMPMn)

| | |
|---------------|--|
| Variable | TEMPMn (where n = 0-15 for channels 1-16) |
| Valid Values | any real number |
| Default Value | none |
| Data Type | float |
| Group | Pressure variables (List G) |
| Description | <p>The “M” term in the conversion equation used to convert temperature counts to degrees Celsius. The conversion formula is:</p> $EC = \frac{Counts \& TempB}{TempM}$ <p>This variable is used only as a placeholder for legacy compatibility.</p> |

TEMPERATURE COEFFICIENTS (LIST TEMP)

TEMPERATURE COEFFICIENTS (TEMPN)

| | |
|---------------|---|
| Variable | TEMP <chan> <point> <temperature> <counts> |
| Valid Values | <chan> 0 to 15 <point> 0 to 100 <temperature> 0 to 70, 100 <counts> -32768 to 32768 |
| Default Value | <chan> 0 to 15, variable <point> 0 to 11, variable <temperature> 100 <counts> 0 |
| Data Type | varies |
| Group | Temperature coefficient variables (List TEMP) |
| Description | <p>Sets the temperature coefficients for each channel. Coefficients listed here are of the later, multi-segment linear interpolation style implemented in firmware version 1.19. Any temperature point listed with a temperature of 100 or greater is discarded. If no temperature data exists for a channel (being all 11 temperature points are set to a temperature of 100) the legacy style TEMP M and TEMP B terms are used.</p> |

ZERO OFFSETS (LIST Z)

ZERO OFFSET (ZERON)

| | |
|---------------|--|
| Variable | ZEROn (where n = 0-15 for channels 1-16) |
| Valid Values | -32768 to 32768 |
| Default Value | none |
| Data Type | integer |
| Group | Pressure variables (List Z) |
| Description | <p>The zero correction for channels 0 - 15. These values are set during the original calibration and fill.</p> |

DSA-PTP PACKET DEFINITIONS

When requested the DSA-PTP sends an application packet to the client. Each packet sent to the client starts with a Packet Type Word. This word defines the packet type.

PACKET TYPES

| Packet Name | Packet ID | Bytes | Notes |
|-----------------|-----------|----------|---|
| Scan | 1Hex | 304 | Binary scan packet (NOT USED) |
| Status | 3Hex | 180 | Long status packet |
| Scan Raw | 4Hex | 72 | Transmits pressure and temperature data in binary, raw counts |
| Scan EU | 5Hex | 104 | Transmits pressure and temperature data in binary, engineering units |
| Scan Raw - Time | 6Hex | 80 | Transmits pressure data in binary, raw counts with a time stamp |
| Scan EU - Time | 7Hex | 112 | Transmits pressure data in binary, engineering units with a time stamp |
| ASCII | 20Hex | Variable | Text packet may be formatted or un-formatted. The format is determined by the setting of FORMAT configuration variable. NOTE: When the first integer of the packet is 20Hex or greater, the packet is assumed to be in ASCII format. |

HOST TO DSA-PTP COMMAND PACKET

| Function Description | Bytes | Data Type | Values |
|---|----------|-----------|---|
| ASCII command data (refer to the command section of this manual for more information) | 1 to 512 | String | Unique to packet. Each line must be terminated with a <CR>, <LR>, <CR-LF> or <LF-CR> |

DSA-PTP TO HOST SCAN PACKET (NOT USED)

| Function Description | Bytes | Data Type | Value/Notes |
|--|-------|-----------|-------------------------|
| Packet Type | 2 | Integer | 1Hex |
| Pad Bytes (forces quad byte alignment) | 2 | Integer | undefined |
| Module Name | 20 | char[20] | (note used) (note used) |
| Channels 1 through 8 - Minimum Pressure | 4 | Float | (note used) |
| Channels 9 through 16 - Minimum Pressure | 4 | Float | (note used) |
| Channels 1 through 8 - Maximum Pressure | 4 | Float | (note used) |
| Channels 9 through 16 - Maximum Pressure | 4 | char[12] | Type of Scan |
| Pressure Type | 12 | char[12] | Scan Units |
| Pressure Units | 12 | char[12] | Temperature Units |
| Temperature Type | 12 | char[12] | Current DSA-PTP Status |
| Status | 20 | char[20] | Current DSA-PTP Errors |
| Error | 60 | char[60] | |
| Perido | 2 | Integer | |
| Skip Frames | 2 | Integer | |
| Average | 2 | Integer | |
| Year | 2 | Integer | |
| Month | 2 | Integer | |
| Day | 2 | Integer | |
| Hour | 2 | Integer | |
| Minute | 2 | Integer | |
| Second | 2 | Integer | |
| Millisecond | 2 | Integer | |
| Channels 1-16 Pressures | 64 | Float | 4 bytes per channel |
| Channels 1-16 Temperatures | 64 | Integer | °C, 4 bytes per channel |

STATUS PACKET

| Function Description | Bytes | Data Type | Value/Notes |
|--|-------|-----------|------------------------|
| Packet Type | 2 | Integer | 3Hex |
| Pad bytes (forces quad byte alignment) | 78 | Integer | unidentified |
| Status | 20 | char[20] | Current DSA-PTP Status |
| Pad bytes (forces quad byte alignment) | 80 | Integer | (not used) |

SCAN RAW PACKET

| Function Description | Bytes | Data Type | Value/Notes |
|--|-------|-----------|----------------------|
| Packet Type | 2 | Integer | 4Hex |
| Pad bytes (forces quad byte alignment) | 2 | Integer | unidentified |
| Frame Number | 4 | Integer | Current Frame Number |
| Channels 1-16 Pressure | 32 | Integer | 2 bytes per channel |
| Channels 1-16 Temperature | 32 | Integer | 2 bytes per channel |

SCAN EU PACKET

| Function Description | Bytes | Data Type | Value/Notes |
|--|-------|-----------|-------------------------|
| Packet Type | 2 | Integer | 5Hex |
| Pad bytes (forces quad byte alignment) | 2 | Integer | unidentified |
| Frame Number | 4 | Integer | Current Frame Number |
| Channels 1-16 Pressure | 64 | Float | 4 bytes per channel |
| Channels 1-16 Temperature | 32 | Integer | °C, 2 bytes per channel |

SCAN RAW WITH TIME PACKET

| Function Description | Bytes | Data Type | Value/Notes |
|--|-------|-----------|--------------------------------------|
| Packet Type | 2 | Integer | 6Hex |
| Pad bytes (forces quad byte alignment) | 2 | Integer | unidentified |
| Frame Number | 4 | Integer | Current Frame Number |
| Channels 1-16 Pressure | 32 | Integer | 2 bytes per channel |
| Channels 1-16 Temperature | 32 | Integer | 2 bytes per channel |
| Time in milliseconds or microseconds | 4 | Integer | 2 bytes |
| Time Units | 4 | Integer | 1 = microseconds 2 = milliseconds |

SCAN EU WITH TIME PACKET

| Function Description | Bytes | Data Type | Value/Notes |
|--|-------|-----------|--------------------------------------|
| Packet Type | 2 | Integer | 7Hex |
| Pad bytes (forces quad byte alignment) | 2 | Integer | unidentified |
| Frame Number | 4 | Integer | Current Frame Number |
| Channels 1-16 Pressure | 64 | Float | 4 bytes per channel |
| Channels 1-16 Temperature | 32 | Integer | °C, 2 bytes per channel |
| Time in milliseconds or microseconds | 4 | Integer | 2 bytes |
| Time Units | 4 | Integer | 1 = microseconds 2 = milliseconds |

ASCII PACKET

| Function Description | Bytes | Data Type | Value/Notes |
|---|-----------|-----------|---|
| ASCII data (the first two bytes must NOT be 1Hex through 1FHex). Refer to the Command Section of this manual for the proper Command return formats. | 1 to 1492 | String | Unique to packet. Each line must be terminated with a <CR>, <LR>, <CR-LF> or <LF-CR> |

This packet will be transmitted when the host issues one of the following commands:

1. SCAN with BIN set to 0
2. LIST n
3. ERROR
4. STATUS

ASCII PACKET EXAMPLES

The following shows the format of the ASCII DATA portion of the List Packet in response to a LIST MASTER (LIST M):

```
INSERT <temp> <chan> <press> <press counts> /M
INSERT <temp> <chan> <press> <press counts> /M
      :           :           :           :
INSERT <temp> <chan> <press> <press counts> /M
```

When a LIST ALL is commanded, Master and Calculated planes are listed. The Master items will have a /M suffix. The following is an example of a LIST ALL (LIST A) command:

```
INSERT <temp> <chan> <press> <press counts>/M
INSERT <temp> <chan> <press> <press counts>/M
      :           :           :           :
INSERT <temp> <chan> <press> <press counts>/M
```

For examples of the ASCII Packets returned from a SCAN command, refer to the SCAN command.

NETWORK PROTOCOLS SUPPORTED

Physical Layer : 10Base-T IEEE 802.3

Link Layer: INTERNET Protocol (IP)

Transport Layer: Transmission Control Protocol (TCP)
User Datagram Protocol (UDP)

DSA3200-PTP BOOT PARAMETERS

To view the DSA3200-PTP module's boot parameters:

1. De-energize the DSA3200-PTP. Connect the DSA3200-PTP trigger/serial test cable (Scanivalve part #155829) from the DSA3200-PTP to a host PC.
2. Start HyperTerminal, or an equivalent communication program. Connect the DSA3200-PTP to a COM port on the PC Host. Set the serial parameters to 9600 BAUD, no parity, 8 data bits and 1 stop bit.
3. Energize the DSA3200-PTP.
4. Type: LIST IP<ENTER>
The IP Address and boot parameters should now be displayed

CHANGING BOOT PARAMETERS (INCLUDING IP ADDRESS)

To change any of the boot parameters:

1. De-energize the DSA3200-PTP. Connect the DSA3200-PTP trigger/serial test cable (Scanco part #155829) from the DSA3200-PTP to a host PC.
2. Start HyperTerminal, or an equivalent communication program. Connect the DSA3200-PTP to a COM port on the PC Host. Set the serial parameters to 9600 BAUD, no parity, 8 data bits and 1 stop bit, no flow control.

3. Energize the DSA3200-PTP.

4. Once booted up, type: LIST IP<ENTER>

5. To change the IP Address, type:

SET IPADD XXX.XXX.XXX.XXX<ENTER> where XXX.XXX.XXX.XXX is the IP Address of the DSA-PTP

6. After all changes have been made they must be saved. to save the changes, type:

SAVE IP <ENTER>

7. The DSA-PTP will respond with "Saving group ip".

8. Power cycle the DSA to use the new IP Address

Alternatively, the DSA-PTP IP address can be changed by connecting to the scanner via Ethernet and changing the IPADD variable in LIST IP, performing a SAVEIP and rebooting the DSA.

DSA3200-PTP BUFFER DESCRIPTION

The DSA3200-PTP buffer is a software buffer. It is set up as a FIFO. It is factory set to hold 10000 averaged frames of data. Each frame uses 292 bytes of memory.

The software buffer is always in use regardless of the setting of QPKTS variable. The effect of QPKTS occurs when the buffer is filled. If QPKTS is set to 1, the scan will stop when the buffer is full. If QPKTS is set to 0, subsequent frames will be discarded when the buffer is full.

The buffer is the liaison between the scan task and the scan output task. The scan output task has a higher priority than the scan task. Under initial conditions, when the buffer is empty, the scan task places one frame of data in the buffer. It then signals the scan output task to read the buffer until it is empty. However, when multiple frames of data are in the buffer, the output task continues until the buffer is empty. Multiple frames of data will accumulate if the scan output task is blocked by the network while outputting data.

DSA-PTP NETWORK CONFIGURATIONS

The DSA-PTP may be configured in three basic network arrangements:

ISOLATED NETWORK

The isolated DSA-PTP network provides the fastest possible data throughput because other network traffic has been eliminated. DSA-PTP commands are issued from the network client/host and data is directed to the network client/host in UDP format. Data is removed from the client/host via disk or tape. This configuration is ideal for high speed data transfer with data reduction that is handled by the network client/host.

INTEGRATED WITH SYSTEM NETWORK

The integrated DSA-PTP provides the most accessible data

to all network clients. Any client/host on the network may control any or all of the DSA's. Network throughput (TCP/IP) may be reduced because of other network traffic. This configuration is ideal for systems that can tolerate slower data transfer rates but require easy access by multiple client/hosts to each DSA-PTP unit.

SUB-NETWORK WITH GATEWAY

The DSA-PTP sub-network allows high speed data transfer of the sub-network while allowing access by a larger network. The gateway is most effective as a multi homed client/host that can store the DSA-PTP data for later access by client/hosts on the main system network.

DSA-PTP NETWORK ADDRESSING

Each DSA-PTP module has the capability to accept commands in Unicast (only one DSA-PTP accepts command)

Each DSA-PTP module has a unique, factory set, 48 bit physical Ethernet address. When running TCP/IP protocol the DSA-PTP modules support ARP (address resolution protocol) to enable the client/host to determine the relationship between the IP address and the Ethernet address. The IP address is user assignable.

SECTION 6: MAINTENANCE

CALIBRATION

The DSA3200-PTP series uses a well proven, very stable, temperature compensated TO-8 style piezoelectric pressure sensor. The use of this series of sensors, along with the ability to perform frequent, online zero offset calibrations allows the DSA-PTP to hold published accuracy for up to 6 months. Scanivalve recommend validating the DSA-PTP with a high-accuracy pressure standard on 6 month intervals and recalibrating the unit as required.

Every DSA-PTP module is calibrated from the factory over a series of 9 temperatures between 0°C and 69°C. At each temperature, 9 pressures are applied. This calibration creates a matrix of discrete temperatures and pressures, called Master Calibration Coefficients. The DSA-PTP then interpolates between each of these points to create a complete matrix of “calculated” coefficients.

When recalibrating a DSA-PTP module, there are three types of calibrations that can be performed:

FULL CALIBRATIONS

A full calibration deletes all calibration coefficients and re-applies known pressures over a series of temperatures. This duplicated exactly what is done at the factory during the module’s original manufacture and calibration. This calibration requires an environmental chamber capable of reaching the entire 0°C and 69°C range and a suitable pressure standard. It is recommended that for a full calibration the module be returned to Scanivalve or a certified Scanivalve Representative.

FIELD CALIBRATIONS

As an alternative to Full Calibrations, Scanivalve offers a free program called “PressCal” that allows any metrology lab with a suitable pressure standard to perform a “Field Calibration.” During a field calibration, a series of pressures are applied to the module at a single temperature. The temperature of the module does **not** have to be controlled to a specific temperature. PressCal calculates a new set of coefficients for that given temperature, then applies a correction to the pressure coefficients across all temperatures. This technique is suitable for maintaining modules long term and has been proven to be just as good as a new full calibration when done properly. More information on PressCal can be found on the Scanivalve website or by contacting Scanivalve.

ZERO OFFSET CALIBRATION

In all piezoelectric pressure sensors, zero drift is the single largest contributor to long term errors. Because of this, all DSA3217-PTP and 3218 modules have internal calibration valves and a software command (CALZ) that allow for a zero offset calibration to be performed easily and frequently. More information on the Zero Offset Correction calibrations can be found in “Zero Offset Calibration” on page 14, and information on the CALB and CALZ commands can be found in “Calibrate Barometric Pressure” on page 24 and “Calibrate Zero” on page 25 respectively.

SPECIAL PROCEDURES

This section contains the procedures to update the firmware, add calibration coefficients to memory. The DSA-PTP should be in the READY mode while these changes are being made. This will have no effect on the operation. The procedures described in this section are written for use in a Windows 7 operating system.

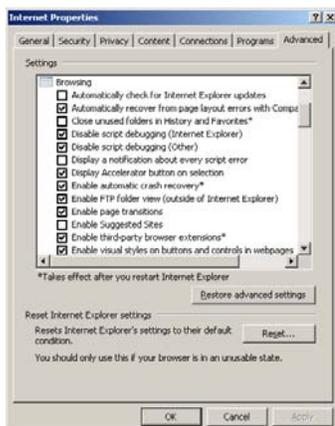
The firmware and coefficient procedures that follow may not function correctly if Windows Internet Explorer is not set up correctly. A user should verify these settings before attempting these procedures.

INTERNET EXPLORER SETUP

1. Open Internet Explorer.
2. Click on Tools
3. Select Internet Options from the drop down menu. The Internet Options window will open.
4. Click on the Advanced Tab to show the Advanced Settings.

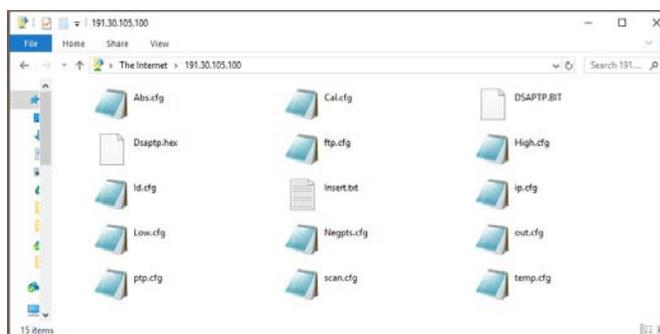


5. Scroll down to the Heading marked "Browsing"
6. Make sure that the line "Enable FTP Folder View (Outside of Internet Explorer)" is checked. If this is not enabled, Internet Explorer will block FTP file transfers.
7. Click OK to accept the settings.

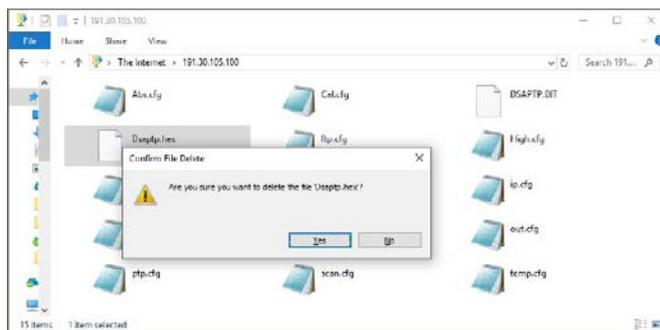
**DSA-PTP FIRMWARE INSTALLATION (WINDOWS 7 & 10)**

NOTE: Some firewalls may block file transfers. We recommend that firewalls be shut down for the procedures in this section.

1. Connect a host computer to the Ethernet port.
2. Install the disk with the New or updated firmware (Dsaptp.Hex) into a drive.
3. Open My Computer
4. In the Address Bar, type:
ftp://<IPAddress><Enter>
Where: <IPAddress> is the IP Address of the DSA-PTP.
5. The host computer should connect, If the connection is successful, the contents of the DSA-PTP memory will be displayed in a folder format.



6. Highlight the existing Dsaptp.Hex file. Right Click on it and select Delete. A window will open to confirm the delete. Click Yes to delete the file.



7. Open Windows Explorer in another window. Find the directory where the new Dsaptp.Hex file is stored. Highlight the file and
Click: Edit
Click: Copy
8. Select the DSA-PTP window and,
Click: Edit
Click: Paste

The file will be copied to the DSA-PTP. A progress window will provide progress information.

9. When the copy function is complete, the DSA-PTP-window will show the new file. The time and date will

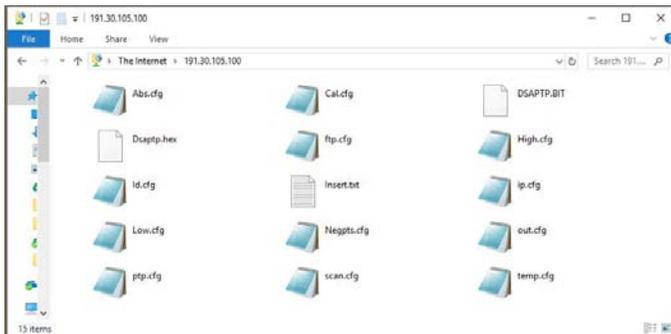
show the Time and Date of the transfer. This is the only time this date will be shown and will change to the default after power cycle.

10. Cycle the AC power or execute a Reboot command to complete the process.

DSA-PTP COEFFICIENT UPLOAD

NOTE: Some firewalls may block file transfers. We recommend that firewalls be shut down for the procedures in this section.

1. Connect a host computer to the Ethernet port.
2. Open My Computer
3. In the Address Bar, type:
ftp://<IPAddress><Enter>
Where: <IPAddress> is the IP Address of the DSA-PTP.
4. The host computer should connect. If the connection is successful, the contents of the DSA-PTP memory will be displayed in a folder format.



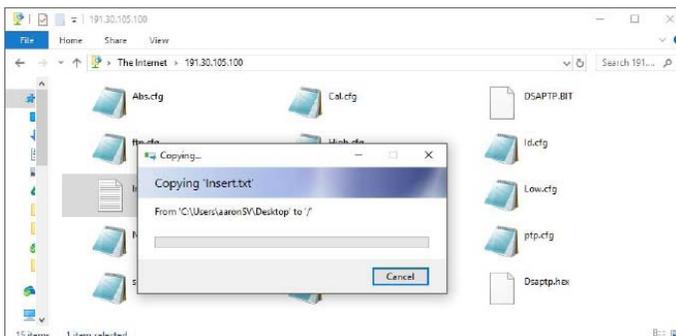
5. Open Windows Explorer in another window. Find the directory where the Cal.cfg file is stored. Highlight the file to be copied to the DSA-PTP and

Click: Edit
Click: Copy

6. Select the DSA-PTP window and,

Click: Edit
Click: Paste

The files will be copied to the DSA-PTP. A progress window will provide progress information.



7. When the copy function is complete, the DSA-PTP-window will show the new files. The time and date will show the Time and Date of the transfer. This is the only time this date will be shown and will change to the default after power cycle.

8. Cycle the AC power or execute a Reboot command to complete the process.

DSA3200-PTP SENSOR REPLACEMENT

The piezoelectric pressure sensors in the DSA-PTP module are field replaceable. If a sensor needs to be replaced, contact Scanivalve Technical Support before attempting to change a sensor. New sensors can be obtained from Scanivalve or any official Scanivalve Representative. Extreme caution should be taken when changing a sensor.



CAUTION! ESD protection is required for this procedure. Failing to follow ESD protection guidelines could cause permanent damage to the DSA-PTP electronics.

The procedure shows a DSA3217-PTP module, but the procedure is very similar for a DSA3218-PTP. Simply remove the top and side of the DSA3218-PTP enclosure, remove the “core” assembly and pick up the procedure at step 4.

The following equipment is required:

- ESD protection
- #1 phillips screw driver
- #2 phillips screw driver
- 5/64” allen wrench
- 3/32” allen wrench

Step 1: Remove the bottom mounting plate

Using a #2 phillips screwdriver, remove the 4 screws that attach the bottom mounting plate.

FIGURE 6.11: REMOVE BOTTOM MOUNTING PLATE**Step 2: Remove the top plate**

Using a 3/32” allen wrench, remove the 8 allen screws holding the top plate on. These are “captive” screws so they do not have to be completely removed.

FIGURE 6.12: REMOVE TOP PLATE**Step 3: Remove the case half screws**

Using a #2 phillips screwdriver, remove the two remaining screws that are securing the two case halves together.

FIGURE 6.13: REMOVE THE CASE HALVE SCREWS**Step 4: Separate the case halves**

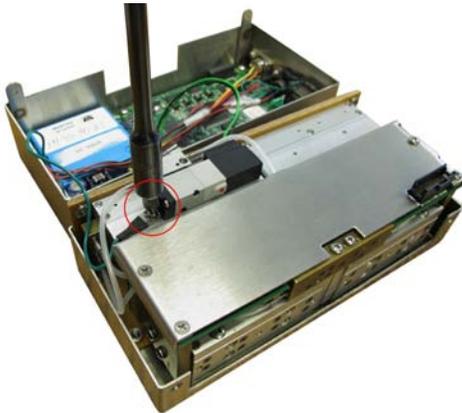
Gently separate the two case halves from each other. Make sure to pull squarely to prevent damage to the A/D board interface connector.

FIGURE 6.14: SEPARATE THE CASE HALVE SCREWS

Step 5: Disconnect the ground wire

Using a #1 phillips screwdriver, disconnect the ground wire.

FIGURE 6.15: REMOVE THE GROUND WIRE



Step 6: Disconnect the Quick Zero solenoid

Carefully disconnect the quick zero solenoid from the processor board.

FIGURE 6.16: DISCONNECT THE QUICK ZERO SOLENOID



Step 7: Remove the "core" from the case half

Using a #2 phillips screwdriver, remove the 4 screws that hold the core into the case half. Carefully remove the core from the case half.

FIGURE 6.17: REMOVE THE CORE



Step 8: Remove the insulators

Using a #2 phillips screwdriver, remove the 8 counter sunk screws that hold the insulators in place.

FIGURE 6.18: REMOVE THE INSULATORS



Step 9: Remove the Quick Zero Solenoid and manifold

Using a 5/64" allen wrench, remove the quick zero solenoid and the manifold from the end of the core.

*NOTE: Only the manifold from the related sensor pack needs to be removed. If changing a sensor in position 1-8, the quick zero solenoid can be left in place.

FIGURE 6.19: REMOVE THE MANIFOLD



Step 10: Remove the reference manifold

Using a #2 phillips screwdriver, remove the reference manifold from the appropriate sensor pack. Gently and squarely pull the reference manifold from the sensor housing.

FIGURE 6.20: REMOVE THE REFERENCE MANIFOLD

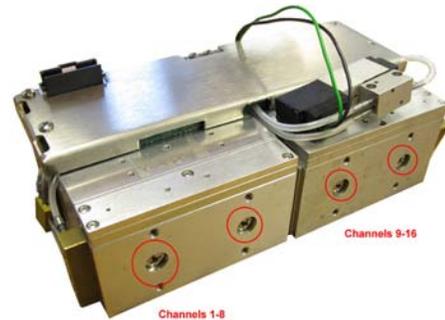
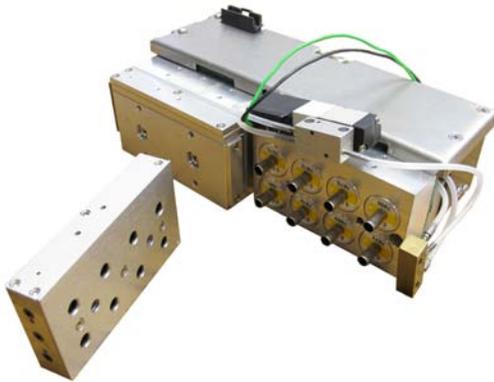


FIGURE 6.21: REMOVE THE REFERENCE MANIFOLD**Step 11: Replace the sensor**

Gently pull the sensor out that needs to be replaced.

Note the position of the alignment pin when installing the new sensor. The sensor shown removed in this image is from position #15.

FIGURE 6.22: REMOVE THE SENSOR

Reassemble the module in the reverse order as the disassembly process. After replacing a sensor, the new calibration coefficients for that sensor will need to be uploaded to the module in order for it to work properly. Scanivalve provides a free utility program called the "Sensor Replacement Utility" that makes this task very simple. The Sensor Replacement Utility can be downloaded for free from the Scanivalve website at <http://www.scanivalve.com/support/software-downloads/>.

DSA3200-PTP GENERAL CHECKOUT

PROCEDURE

The following is a high-level checkout procedure for the DSA3200-PTP series modules. This can be used as a verification that the module is fully functional before implementing it into a system, or as a diagnostic check if it is suspected that the module is not functioning correctly. Ensure that the module has been warmed up for at least 1 hour before beginning this procedure. This procedure does not verify the accuracy of the module. If the module fails this procedure in any way, contact Scanivalve for additional support.

Begin by configuring the module for the test, with the following settings:

| | |
|-----------------------|------------------------|
| SET FORMAT 0 | SET FPS 2 |
| SET AVG 32 | SET XSCANTRIG 0 |
| SET PERIOD 500 | SET BIN 0 |

Verify that the unit is not configured for UDP data by sending the command:

LIST I

Check the setting of the HOST variable. If the last character is a "U" then the unit needs to be reconfigured before beginning this checkout. Change the last character to "T", then type SAVE. Once the save is complete, cycle power on the module.

1. Check raw pressure and temperature readings

Send the following commands:

SET EU 0
SET ZC 0
SCAN

- The raw pressure readings should all be ± 500 counts
- The raw temperature readings (at room temp) should be between -15,000 and +10,000 counts

2. Verify the CALZ function

Send the following commands:

SET ZC 1
CALZ (wait 10-15 seconds for the CALZ to complete)
SCAN

- The raw pressure readings should all be ± 5 counts

3. Verify the Engineering Unit Conversion

Send the following commands:

SET EU 1
SCAN

- The pressure readings should be extremely close to 0.0psi
- The temperature readings should be between 0°C and

15°C above the ambient temperature, depending on how long it has been powered up.

4. Verify the reference response

Send the following commands:

SET FORMAT 1
SET FPS 0
SCAN

With the unit scanning, apply between 75% and 100% of full scale pressure (or 15 psi maximum) to the reference port(s) on the module.

- This should result in a negative reading on all channels.

5. Check for leaks in the reference plumbing

With the unit still scanning, trap the pressure on the reference port(s).

- Monitor the pressures for 60 seconds, a pressure drop of up to 0.1% of full scale is acceptable.

Vent the pressure off of the reference port(s).

6. Verify individual Px response

With the unit still scanning, apply between 75 and 100% of full scale pressure individually to all 16 Px inputs.

- This should result in a believable positive pressure on only the one channel with pressure applied.

7. Verify the calibration input (CAL) response

Apply 90-120 psi to the CTL1 and CTL2 ports to put the DSA-PTP module into calibration mode.

With the unit still scanning, apply between 75 and 100% of full scale pressure to the CAL port(s)

- This should result in a believable positive pressure on all 16 channels.

8. Check for leaks in the calibration plumbing

With the unit still scanning, trap the pressure on the calibration port(s).

- Monitor the pressures for 60 seconds, a pressure drop of up to 0.1% of full scale is acceptable.

Vent the pressure off of the calibration port(s).

Vent the pressure off the CTL1 and CTL2 ports.

STOP the scan.

9. Check for drifting/unstable sensors

Send the following commands:

SET EU 0

CALZ (wait for the CALZ to complete)

SCAN

Monitor all 16 channels

- All sensor readings should stay stable within 4 counts for 1 minute.

STOP the scan.

10. Check for noisy output

Send the following commands:

SET AVG 4

SCAN

Monitor all 16 channels for 1 minute, watching for any "spiking" data.

- All readings should stay within ± 20 counts from the original reading for the duration of the 1 minute test.

11. OPTIONAL Purge test

Apply 90-120 psi to the CTL1 and CTL2 ports

Apply 90-120 psi to the PRGCTL port

Apply the desired purge pressure to the PRG port

- Verify that purge pressure is flowing out of all 16 Px input ports
- Verify that there is no purge pressure flowing out of any other port

At the completion of the test, step the unit out of purge mode:

Remove the purge pressure from the PRG port

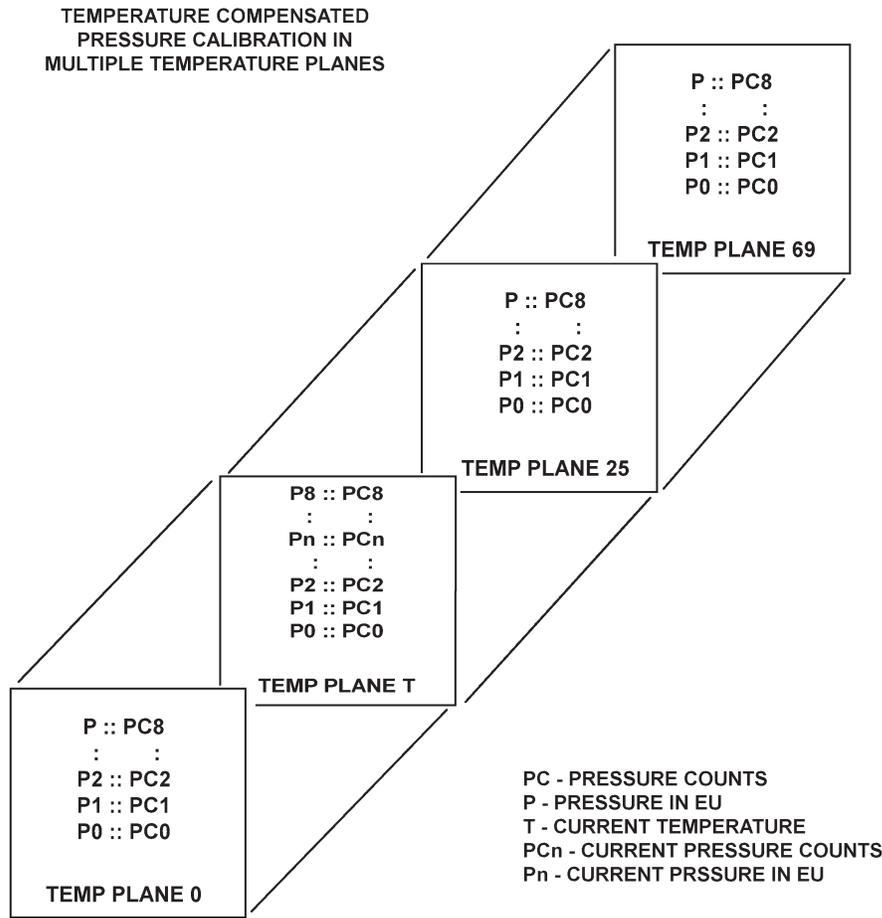
Remove the 90-120 psi from the PRGCTL port

Remove 90-120 psi from the CTL1 and CTL2 ports

[INTENTIONALLY LEFT BLANK]

APPENDIX

APPENDIX A: TEMPERATURE COMPENSATED PRESSURE CONVERSION



Formulas:

Pressure interpolation within current temperature plane:

$$P_{nt} = \frac{1}{PC_{1t} - PC_{0t}} ((PC_{1t} - PC_{nt})P_{0t} - (PC_{0t} - PC_{nt})P_{1t})$$

Calculation of entries in current temperature plane:

$$P_t = \frac{1}{T_{25} - T_0} ((T_{25} - T)P_{00} - (T_0 - T)P_{0.25})$$

APPENDIX B: ENGINEERING UNIT CONVERSION CONSTANTS

| UNITSCAN Setting | Engineering Unit | PSI to EU 1 psi = | EU to PSI 1 EU = |
|------------------|--------------------------------|-----------------------------|---------------------|
| ATM | Atmospheres | 0.068046 A | 14.6960 psi |
| BAR | Bars | 0.068947 b | 14.5039 psi |
| CMHG | Centimeters of Mercury | 5.17149 cmHg | 0.193368 psi |
| CMH2O | Centimeters of Water | 70.308 cmH ₂ O | 0.014223 psi |
| DECIBAR | Decibar | 0.68947 db | 1.4504 psi |
| FTH2O | Feet of Water | 2.3067 ftH ₂ O | 0.43352 psi |
| GCM2 | Gram per square Centimeter | 70.306 g/cm ² | 0.014224 psi |
| INHG | Inch of Mercury @ 0°C | 2.0360 inHg | 0.491159 psi |
| INH2O | Inch of Water @ 4°C | 27.0680 inH ₂ O | 0.36127 psi |
| KGCM2 | Kilogram per square Centimeter | 0.703070 kg/cm ² | 14.2235 psi |
| KGM2 | Kilogram per square Meter | 703.069 kg/m ² | 0.0014223 psi |
| KIPIN2 | kips per square inch (ksi) | 0.001kip/in ² | 1000.0 psi |
| KNM2 | Kilonewton per square Meter | 6.89476 kN/m ² | 0.145038 psi |
| KPA | Kilopascal | 6.89476 kPa | 0.145038 psi |
| MBAR | Millibar | 68.947 mb | 0.014504 psi |
| MH2O | Meter of Water | 0.70309 mH ₂ O | 1.42229 psi |
| MMHG | Millimeter of Mercury | 51.7149 mmHg | 0.0193368 psi |
| MPA | Megapascal | 0.00689476 MPa | 145.039 psi |
| NCM2 | Newton per square Centimeter | 0.689476 N/cm ² | 1.45038 psi |
| NM2 | Newton per square Meter | 6894.76 N/m ² | 0.000145038 psi |
| OZFT2 | Once per square Foot | 2304.00 oz/ft ² | 0.000434028 psi |
| OZIN2 | Ounce per square Inch | 16.00 in/ft ² | 0.062500 psi |
| PA | Pascal | 6894.76 Pa | 0.000145038 psi |
| PSF | Pound per square Foot | 144.00 lb/ft ² | 0.00694444 psi |
| TORR | Torr | 51.7149 T | 0.0193368 psi |

APPENDIX C: DSA3200-PTP ERROR LIST**BOOT/INITIALIZATION ERRORS**

- ERROR: Could not create a socket
 - Fatal Error - The DSA-PTP Module has a hardware problem.
- ERROR: Could not bind a socket
 - Fatal Error - The DSA-PTP Module has a hardware problem.
- ERROR: Could not listen on a socket
 - Fatal Error - The DSA-PTP Module has a hardware problem.
- ERROR: accept slave socket
 - Fatal Error - The DSA-PTP Module has a hardware problem.

SET CONFIGURATION VARIABLE ERRORS

- ERROR: Model value not valid
 - The model value is not 3207, 3217 or 3218
- ERROR: PORT value not valid
 - Port is not a valid Windows Port number
- ERROR: HOST value not found
- ERROR: HOST server port value not valid
 - The host port was not entered or is an invalid or reserved port number
- ERROR: HOST IP address value not valid
 - The host IP address entered is not a valid address
- ERROR: PMaxH value not valid
- ERROR: PMaxL value not valid
 - The value for the variable was not entered or is not numeric.
- ERROR: PMinH value not found
- ERROR: PMinH value not valid
 - The value for the variable was not entered or is not numeric.
- ERROR: PMinL value not found
- ERROR: PMinL value not valid
 - The value for the variable was not entered or is not numeric.
- ERROR: NegPts value not valid
- ERROR: NegPts channel value invalid
 - The value for the variable was not entered or is not numeric.
- ERROR: NegPts channel not between 0 and 15
 - The number entered was negative or greater than 15
- ERROR: NegPtsH value not found
- ERROR: NegPtsH value not valid
 - The value for the variable was not entered or is not numeric.
- ERROR: NegPtsL value not found
- ERROR: NegPtsL value not valid
 - The value for the variable was not entered or is not numeric.
- ERROR: NegPtsH not between 0 and 8
- ERROR: NegPtsL not between 0 and 8
 - The number entered was negative or greater than 8
- ERROR: Abs value not found
- ERROR: Abs value not valid
- ERROR: Abs channel value invalid
 - The number entered was negative or greater than 15
- ERROR: Abs channel not between 0 and 15
 - The number entered was negative or greater than 15
- ERROR: Max value not valid
- ERROR: Max channel value invalid
 - The value for the variable was not entered or is not numeric.

ERROR: Max channel not between 0 and 15
The number entered was negative or greater than 15

ERROR: Min value not valid

ERROR: Min channel value invalid
The value for the variable was not entered or is not numeric.

ERROR: Min channel not between 0 and 15
The number entered was negative or greater than 15

ERROR: Period value not valid
The value for the variable was not entered or is not numeric.

ERROR: Period value below range

ERROR: Period value above range
The value entered was less than 125 or greater than 65535

ERROR: FPS value not valid
The value for the variable was not entered or is not numeric.

ERROR: EU value not valid

ERROR: QPKTS value not valid

ERROR: ZC value not valid

ERROR: BIN value not valid

ERROR: FORMAT value not valid

ERROR: XSCANTRIG value not valid

ERROR: PAGE value not valid

ERROR: ECHO value not valid
The value for the variable was not 0 or 1.

ERROR: TIME value not valid
The value for the variable was not 0, 1 or 2.

ERROR: AVG value not valid
The value for the variable was not entered or is not numeric.

ERROR: Average value below range

ERROR: Average value above range
The value entered was less than 1 or greater than 240

ERROR: UnitScan value not valid
The value for the variable was not entered.

ERROR: UnitScan did not find unit name in table
The value for the variable is not on the master list. Refer to the software specification for a list of valid names.

ERROR: CvtUnit value not valid
The value for the variable was not entered or is not numeric.

ERROR: Tempb value not valid

ERROR: TempB channel value invalid
The value for the variable was not entered or is not numeric.

ERROR: TempB channel not between 0 and 15
The number entered was negative or greater than 15

ERROR: Tempm value not valid

ERROR: TempM channel value invalid
The value for the variable was not entered or is not numeric.

ERROR: TempM channel not between 0 and 15
The number entered was negative or greater than 15

ERROR: SerNum value not valid
The value entered is not numeric

ERROR: Npr value not valid
The value entered is not numeric

ERROR: DEF channel not valid
The channel value entered is negative or not numeric

ERROR: DEF channel not between 0 to 15
The number entered was negative or greater than 15

ERROR: CALB baro value not valid
The value was not entered, negative, or not numeric

ERROR: CALB period value not valid
The value entered was outside the range of the PERIOD variable.

ERROR: CALB average value not valid
The value entered was less than 1 or greater than 240.

ERROR: Calb data error
Fatal hardware error - The module did not enter or complete the scan.

ERROR: CALZ period value not valid
The value entered was outside the range of the PERIOD variable.

ERROR: CALZ average value not valid
The value entered was less than 1 or greater than 240.

ERROR: Calz data error
Fatal hardware error - The module did not enter or complete the scan.

ERROR: Zero value not valid

ERROR: Zero channel value invalid
The value for the variable was not entered or is not numeric

ERROR: Zero channel not between 0 and 15
The number entered was negative or greater than 15

ERROR: Delta value not valid

ERROR: Delta channel value invalid
The value for the variable was not entered or is not numeric

ERROR: Delta channel not between 0 and 15
The number entered was negative or greater than 15

ERROR: Dout channel not present
The DOUT channel and condition was not entered

ERROR: Dout channel invalid
The DOUT channel number entered less than 1, greater than 5, or not numeric.

ERROR: Dout data missing
The DOUT condition was not entered

ERROR: Dout data value not valid
The DOUT condition was not 0 or 1

COMMAND ERRORS

ERROR: Mode ready, invalid command

ERROR: Invalid command
The command entered was not a DSA-PTP command

ERROR: Invalid set parameter
The configuration variable entered was not a DSA-PTP variable

ERROR: Invalid list parameter
The list parameter was not A, B, C, D, G, H, I, L, M, N, O, S, or Z.

ERROR: UPLOAD <S or C> value not found
S or C was not entered or was lower case

ERROR: UPLOAD file name not found
The file name was not entered, does not exist, or has an invalid path

ERROR: Insert's temp value not valid
The temperature values were either not entered, negative, or not numeric

ERROR: Insert's temp above <max temp>
The temperature value entered was greater than 69

ERROR: Insert's chan value not valid
The channel value was not entered or not numeric.

ERROR: Insert's chan above 15
The channel value entered was greater than 15

ERROR: Insert's pressure value not valid

The pressure value entered was not numeric
 ERROR: Insert's type not valid
 ERROR: Insert's type must be M
 The insert type must be M
 ERROR: LIST M start temp not valid
 The start temp entered was less than 0, greater than 69, or not numeric
 ERROR: List M start temp above <max temp>
 The start temp entered was greater than 69
 ERROR: LIST M stop temp not valid
 The stop temp entered was less than start temp, not numeric, or greater than 69
 ERROR: List M stop temp above <max temp>
 The stop temp entered was greater than 69
 ERROR: LIST A start temp not valid
 The start temp entered was less than 0, greater than 69, or not numeric
 ERROR: List A start temp above <max temp>
 The start temp entered was greater than 69
 ERROR: LIST A stop temp not valid
 The stop temp entered was less than start temp, not numeric, or greater than 69
 ERROR: List A stop temp above <max temp>
 The stop temp entered was greater than 69
 ERROR: DELETE start temp value not found
 The start temp was not entered or was not numeric
 ERROR: DELETE start temp not valid
 The start temp entered was less than 0, greater than 69, or not numeric
 ERROR: DELETE stop temp value not found
 The stop temp was not entered or was not numeric
 ERROR: DELETE stop temp not valid
 The stop temp entered was less than 0, greater than 69, or not numeric
 ERROR: Delete start temp above <max temp>
 The start temp entered was greater than 69
 ERROR: Delete stop temp above <max temp>
 The stop temp entered was greater than 69
 ERROR: Max errors exceeded
 The error buffer is full - more than 15 errors have been detected
 ERROR: No Errors
 No errors have been detected - this is the normal response to the error command

COMMUNICATION ERRORS

ERROR: Closing slave socket with read error
 Fatal Error - The DSA-PTP Module has a hardware problem.
 ERROR: Could not spawn Tcp Server
 Fatal Error - The DSA-PTP Module has a hardware problem.
 ERROR: Could not spawn Udp Id Server
 Fatal Error - The DSA-PTP Module has a hardware problem.
 ERROR: Could not spawn Udp Server
 Fatal Error - The DSA-PTP Module has a hardware problem.
 ERROR: Could not create a UDP socket
 Fatal Error - The DSA-PTP Module has a hardware problem.
 ERROR: Could not bind a UDP socket
 Fatal Error - The DSA-PTP Module has a hardware problem.
 ERROR: sending UDP bytes
 Fatal Error - The DSA-PTP Module has a hardware problem.
 ERROR: Alignment error
 Fatal Error - The DSA-PTP Module has a hardware problem parsing the data

ERROR: Allignment rb%lu f%1IX lbx%1IX lb%1IX px%1IX p%1IX cx%1IX c%1IX”,

Fatal Error - The DSA-PTP Module has a hardware problem parsing the data.

ERROR: Data buffer overflow

The data buffer is full - The TCP/IP connection may be disconnected

ERROR: Send message queue

The TCP/IP connection may be disconnected or the scan speed os too fast for the network.

ERROR: Send queue is full

The TCP/IP connection may be disconnected or the scan speed os too fast for the network.

ERROR: Receive message queue

The command received is too long, or too many commands have been sent before the DSA-PTP Module can process them.

APPENDIX D: SOFTWARE CHANGE LOG

Version 1.00 - Released April 2018
Initial Release

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Scanivalve

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**DSA3200-PTP MANUAL
APRIL 14, 2018**